Improved Modeling of Loading Kinetics in Detailed Filter Media Simulations with GeoDict

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Overview

- 1. Motivation peculiar effects observed in experiments
- 2. Hypothetical explanations
- 3. Filtration simulation with GeoDict
- 4. Results



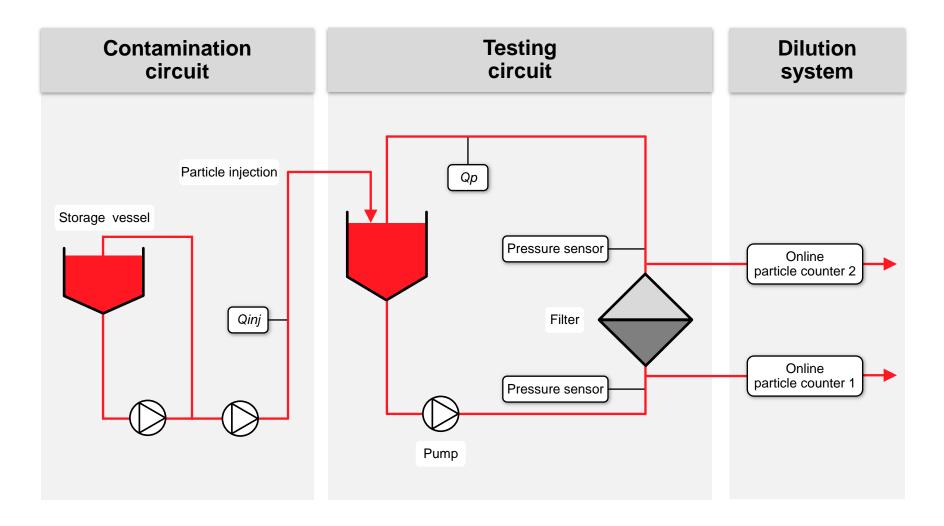


1. Experimental Observations





The Multipass Test (ISO 4548)

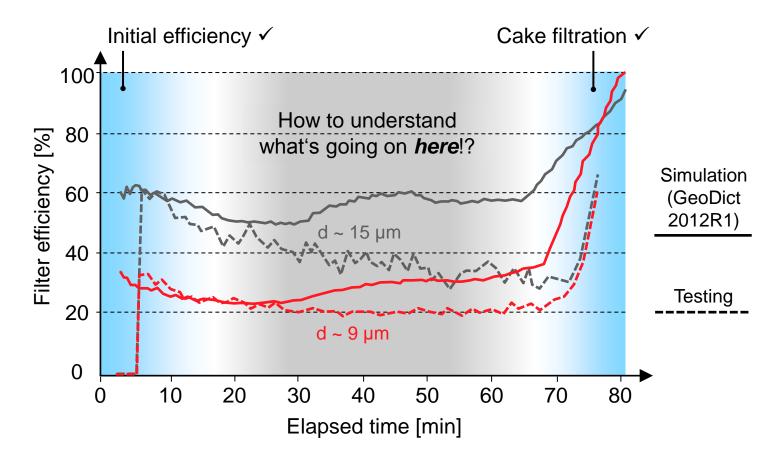






The Multipass Test (ISO 4548)

Peculiarities observed in testing of depth filter media





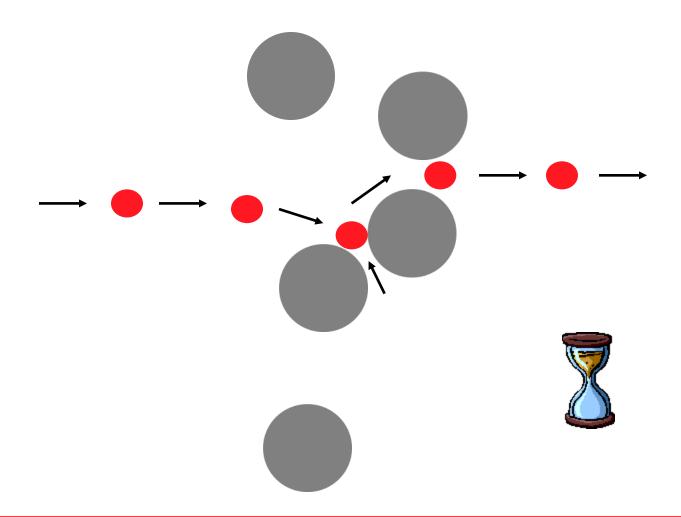


2. Hypothetical Explanations for a Decreasing Efficiency





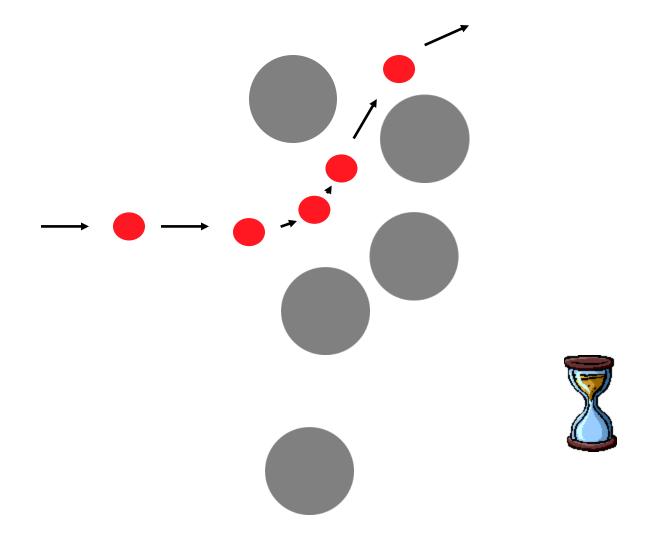
Explanation A: Re-Entrainment







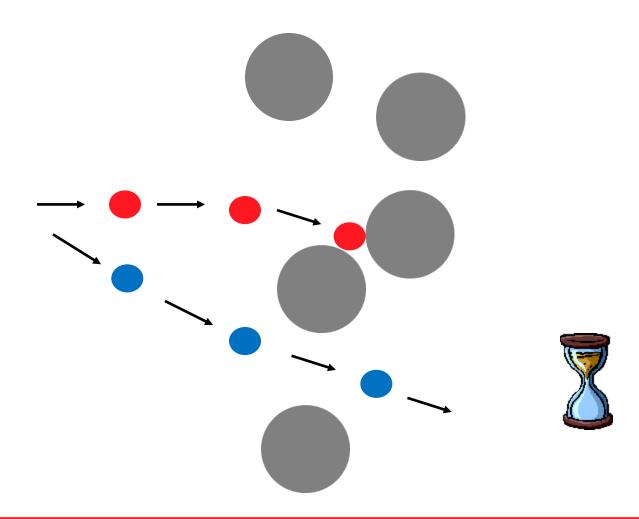
Explanation B: Lingering







Explanation C: Flow Pathways







3. General Approach to Filtration Simulations





Filter Simulation: Efficiency

Basic idea:

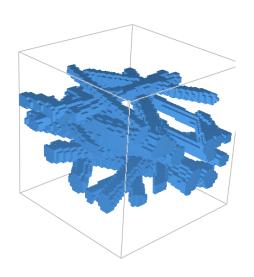
- Filter model
- Determine flow field
- 3. Track particles (filtered or not?)

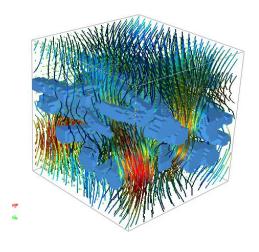
Randomness:

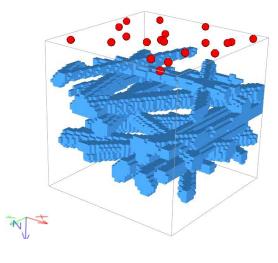
- Starting positions
- Brownian motion

Result:

Percentage of filtered particles











Tracking the Particles

- No interaction between particles
- Flow field is not changed by a moving particle
- Modeled effects:
 - Inertia
 - Brownian motion
 - Electrostatic attraction or repulsion





Adhesion Model

What happens when a particle hits the filter material?

- a) sticks to material (deposited)
- b) bounces off

Particles always stick => Caught on first touch model

Particles always bounce off => **Sieving** model

Particles loose energy when bouncing => **Restitution** factor





Hamaker Model

Adhesive forces: $F_{vdW} = \frac{Hd}{12a^2}$

(van-der-Waals forces between spherical particle and flat surface)

H Hamaker constant [J]d Particle diametera Distance between particle and surface

Escape velocity:

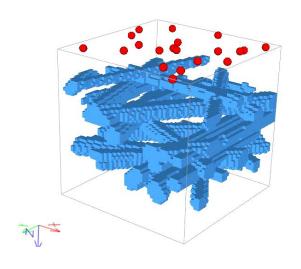
- Integrate from a0 (min distance = 4e-10) to infinity
- Compare with kin. energy of particle

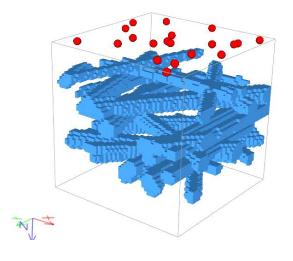
$$v^2 = \frac{H}{4\pi\rho a_0 r^2}$$
 Particle sticks for smaller velocities v.

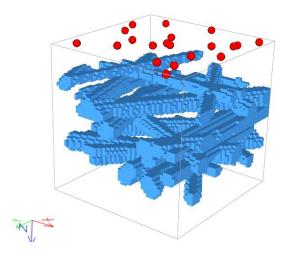




Comparison







Caught on first touch

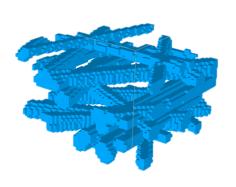
Hamaker H =1e-21 Restitution = 0.5

Sieving

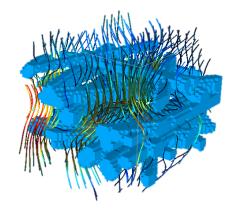




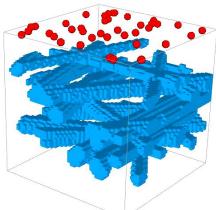
Filter Simulation: Life Time



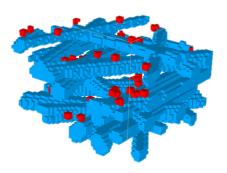
1. Filter Model



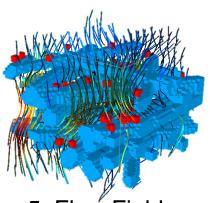
2. Flow Field



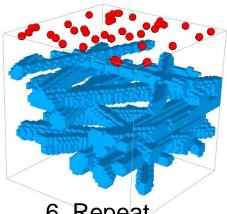
3. Track Particles



4. Deposit Particles



5. Flow Field



6. Repeat ...





Improvements to FilterDict

- Global time concept: particles can continue to the next batch
 - => allows lingering particles
 - => needed for re-entrainment
- More accurate particle tracking
 - 2012R1:
 - flow solver uses staggered grid but writes cell-centered result file particle tracking uses cell-centered file
 - => accuracy lost (especially at no-slip boundary)
 - 2012R2:
 - flow solver uses staggered grid and writes staggered grid result file particle tracking uses staggered grid
- •





Effect of Higher Accuracy: MPPS Simulation Example

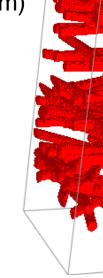
Structure:

- Fibers with diameter 20 µm
- Different porosities
- Different resolutions (voxel length 1 µm 4µm)

Simulation:

- Find efficiency for all particle diameters (caught on first touch, air filtration)
- Brownian Motion: on/off
- Inertia: on/off (by particle weight)
- Different flow velocities



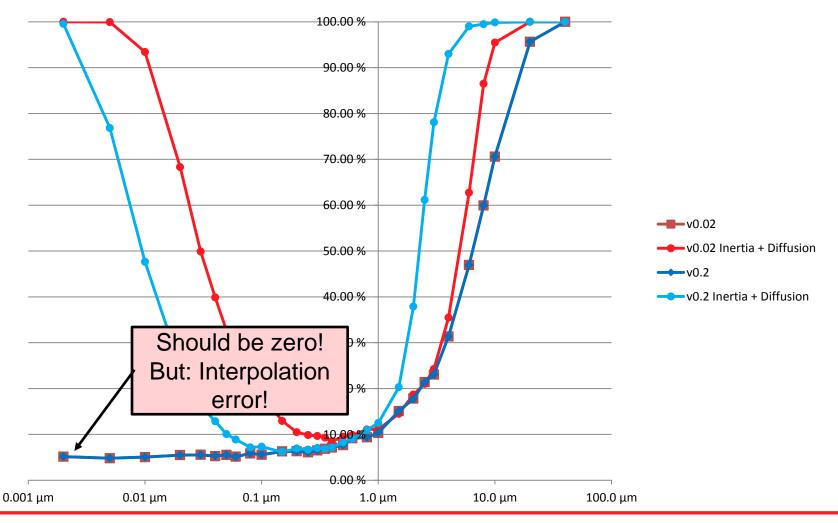






Fixed: Porosity 90%, Resolution 2 μm

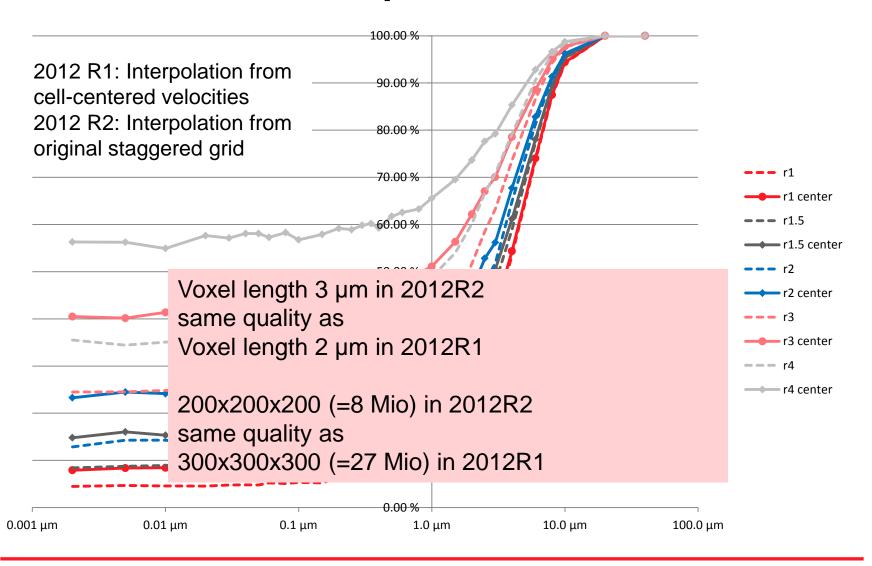
Vary: Velocity







Enhancement of Interpolation in 2012R2





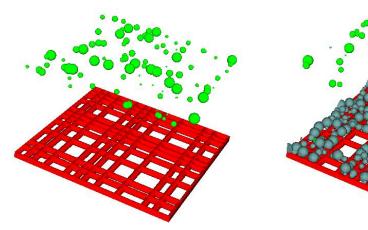


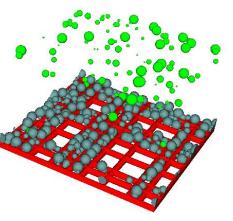
4. Results

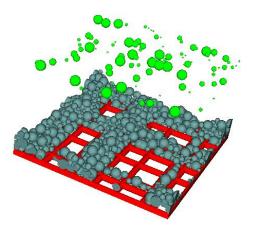




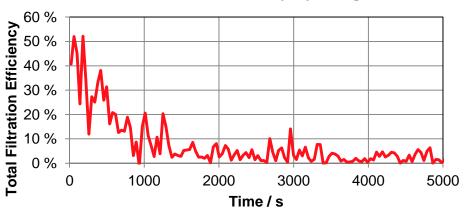
Decreasing Efficiency by Changed Pathways







Total Filtration Efficiency by Weight



=> Effect can explain decreasing efficiencies!





Reentrainment & Lingering

Observations from numerous simulations:

- Larger particles get sieved!
- Local flow field does not flip direction => particles stay sieved.
- => Larger particles do not re-entrain (in significant numbers)!
- Initially, particles pass the clean filter quickly.
- Small particles pass through filter cake slowly (in later stages of filtration, assuming sieving model)
- => This is most likely not the main explanation!

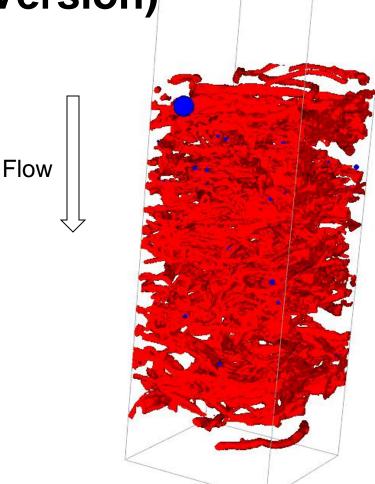




Simulation Results (GeoDict 2012R2 Version)

Tomography cut-out

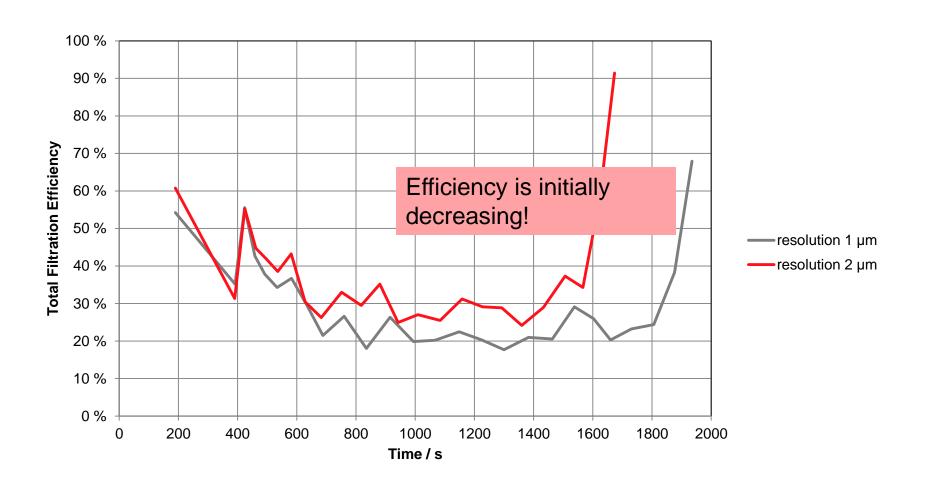
- Oil filtration
- Adhesion model: sieving
- No re-entrainment







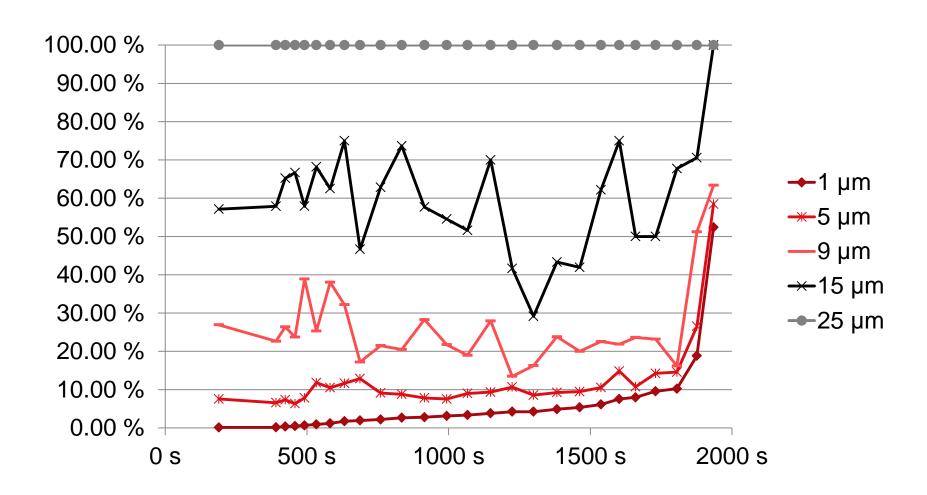
Total Efficiency by Weight







Fractional Filtration Efficiency







Summary and Outlook

Summary:

Decreasing efficiencies can be explained by simulation
No re-entrainment, but explained geometrically

Improvements needed:

- More accurate particle tracking / flow field interpolation
- Global time concept: particles can continue in the next batch

Future improvements:

- Enhance fractional efficiency determination (Filtech 2013)
- Reconsider sieving criterion w.r.t. resolution dependency





Thank You!



The Virtual Material Laboratory

www.geodict.com























