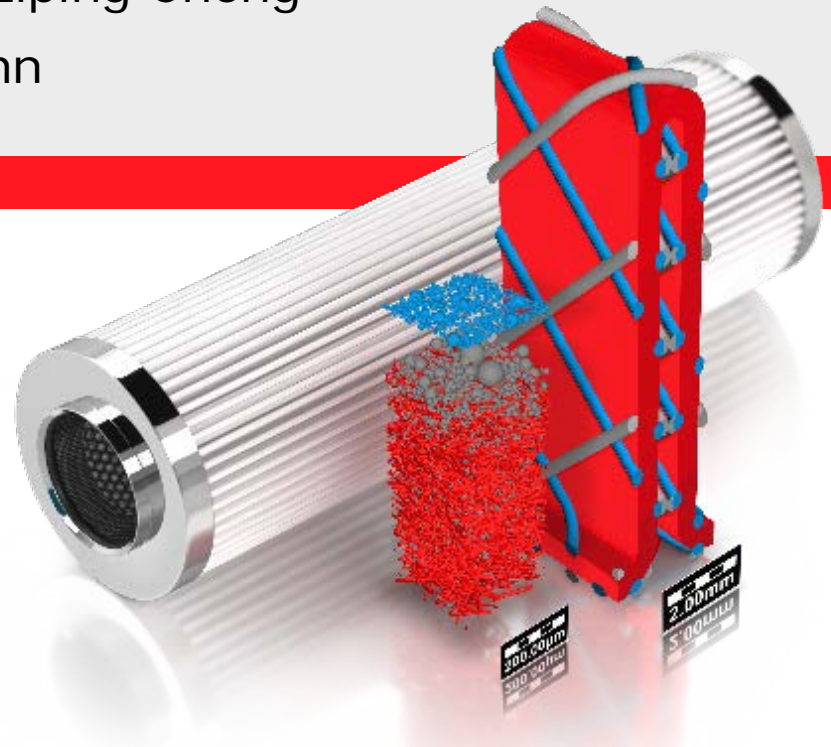


Analysis of Filter Media and Simulation of Filter Processes Based on μ CT Scans

Jürgen Becker, Cornelia Kronsbein, Liping Cheng

Rolf Westerteiger, Andreas Wiegmann



Who is Math2Market ?

- Math2Market GmbH was founded 2011 in Kaiserslautern.
- Spin-off of Fraunhofer Institute for Industrial Mathematics, ITWM.
- Today: 13 full-time, 6 part-time employees, turnover >2 Mio € / year
- Our product: GeoDict software
 - Sales
 - Development and Customization
 - Consulting



What is GeoDict?

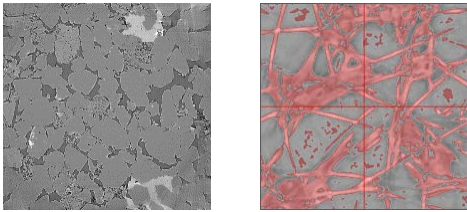
GeoDict is a digital material laboratory

- Computer Aided Material Engineering and Design by providing Geometric models and preDictions of material properties.

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- Computer Aided Material Engineering and Design by providing Geometric models and preDictions of material properties.

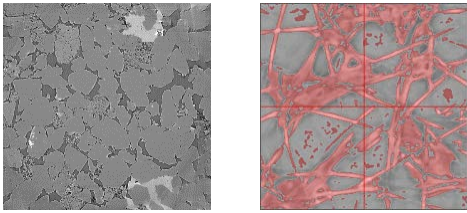


Import of CT Scans

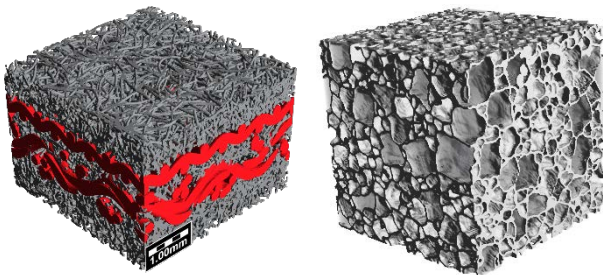
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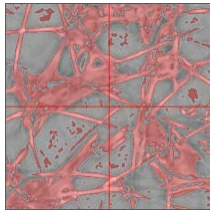
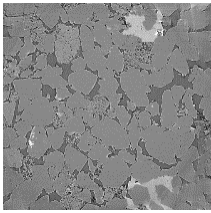


Create 3D Models of
Micro-structures

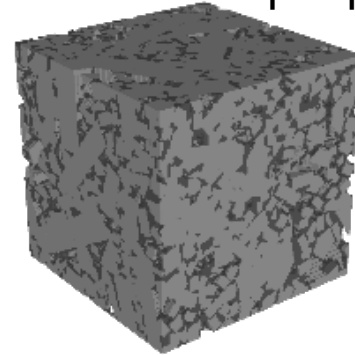
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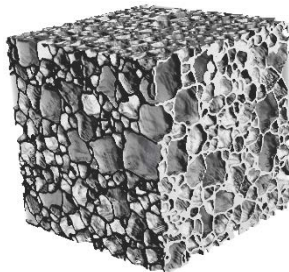
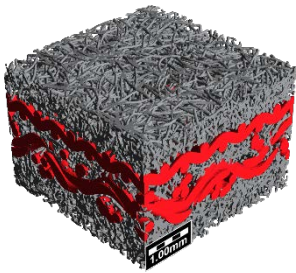
- Computer Aided Material Engineering and Design by providing Geometric models and preDictions of material properties.



Import of CT Scans



Geometric Analysis
of 3D Structures

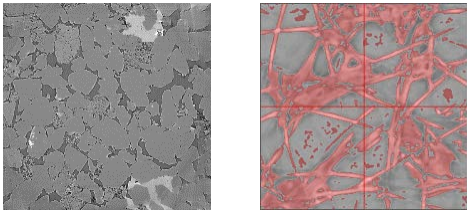


Create 3D Models of
Micro-structures

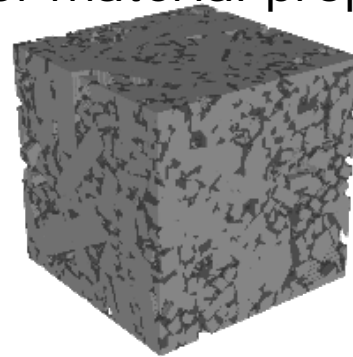
What is GeoDict?

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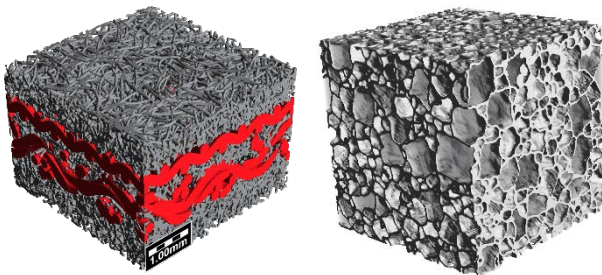
- Computer Aided Material Engineering and Design by providing Geometric models and preDictions of material properties.



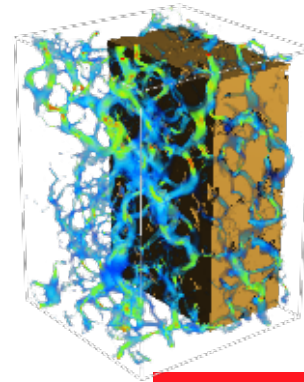
Import of CT Scans



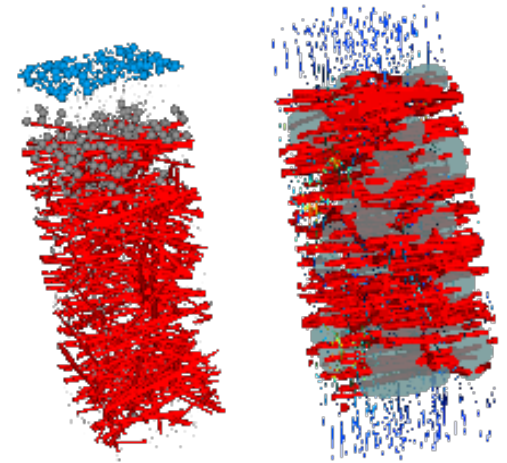
Geometric Analysis
of 3D Structures



Create 3D Models of
Micro-structures



Simulate advection, diffusion
particle transport, stiffness



How can simulations help to improve a filter?

Step 1: Understand the existing filter material

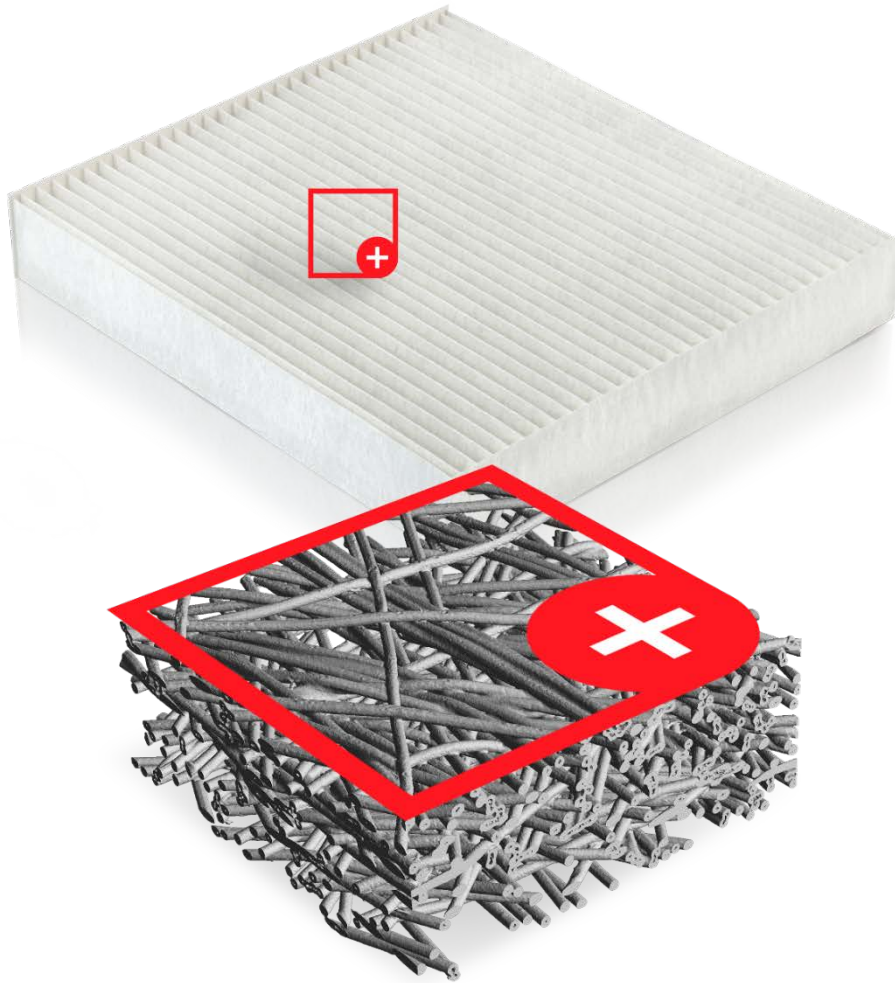
- CT Scan
- Simulations on CT Scan

Step 2: Create a model of the existing material

- Analyze CT Scan
- Create structure model
- Simulations on Structure model

Step 3: Modify the structure model

Sample Structure: Cabin Air Filter



- Commercially available filter
- CT scan by service provider RJI Micro&Analytic

Step 1:

Understand the existing filter material

Determine Flow Rate or Pressure Drop

Stationary Navier-Stokes flow:

$$-\mu \Delta \vec{u} + \rho (\vec{u} \cdot \nabla) \vec{u} + \nabla p = 0$$

(momentum balance)

$$\nabla \cdot \vec{u} = 0$$

(mass conservation)

$$\vec{u} = 0 \text{ on } \Gamma$$

(no-slip on surface)

$$P_{in} = P_{out} + \text{const}$$

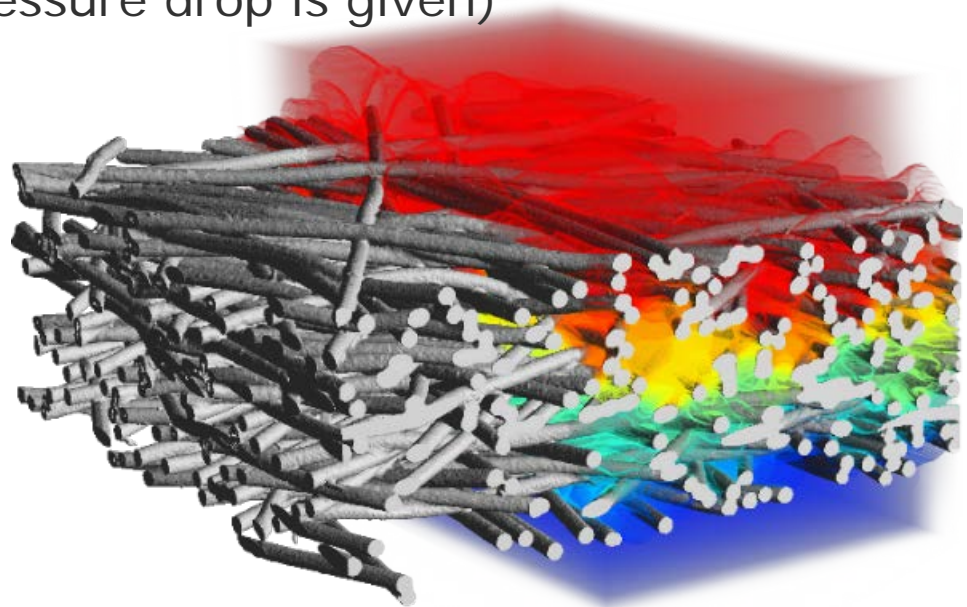
(pressure drop is given)

\vec{u} : velocity

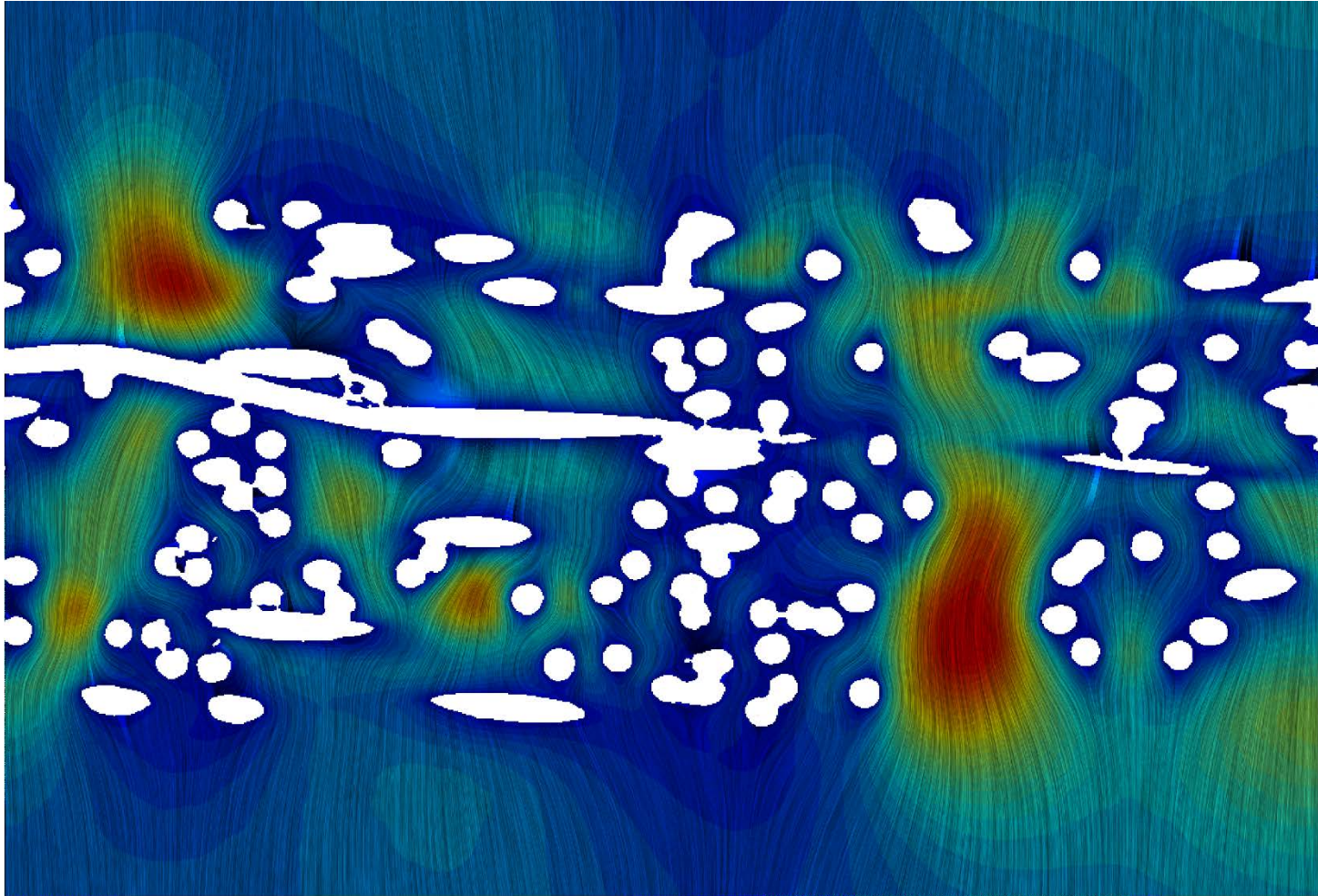
p : pressure

μ : dynamic viscosity

ρ : fluid density

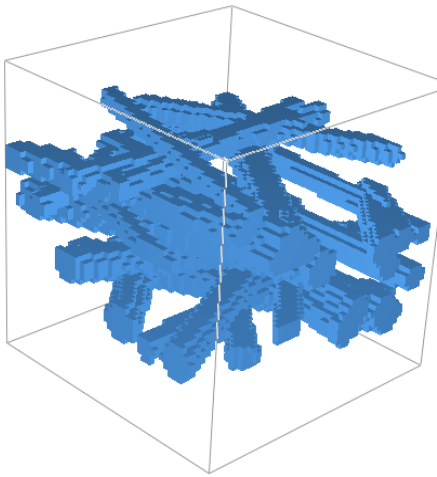


Result for Clean Cabin Air Filter Media (Flat Sheet): Pressure drop of 7.35 Pa at 0.1 m/s mean velocity



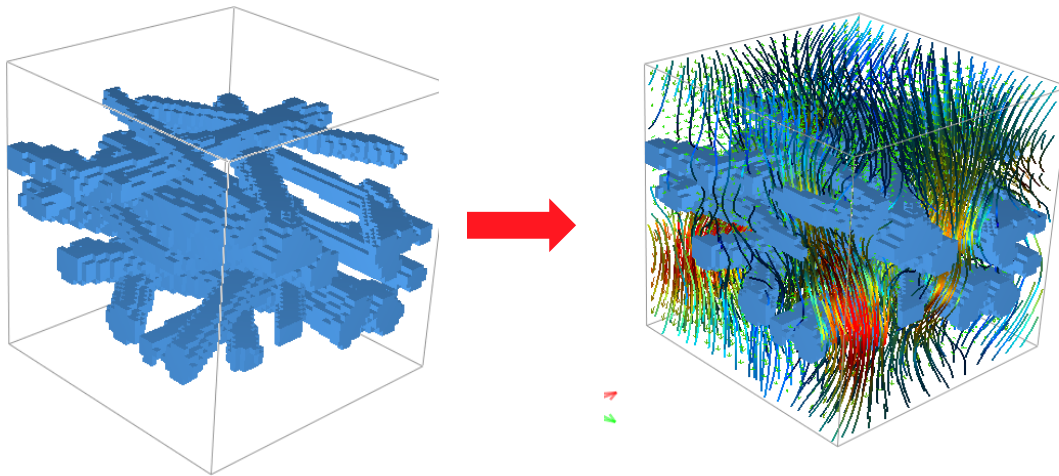
Efficiency of Clean Filter Media: Method

1. Filter media model



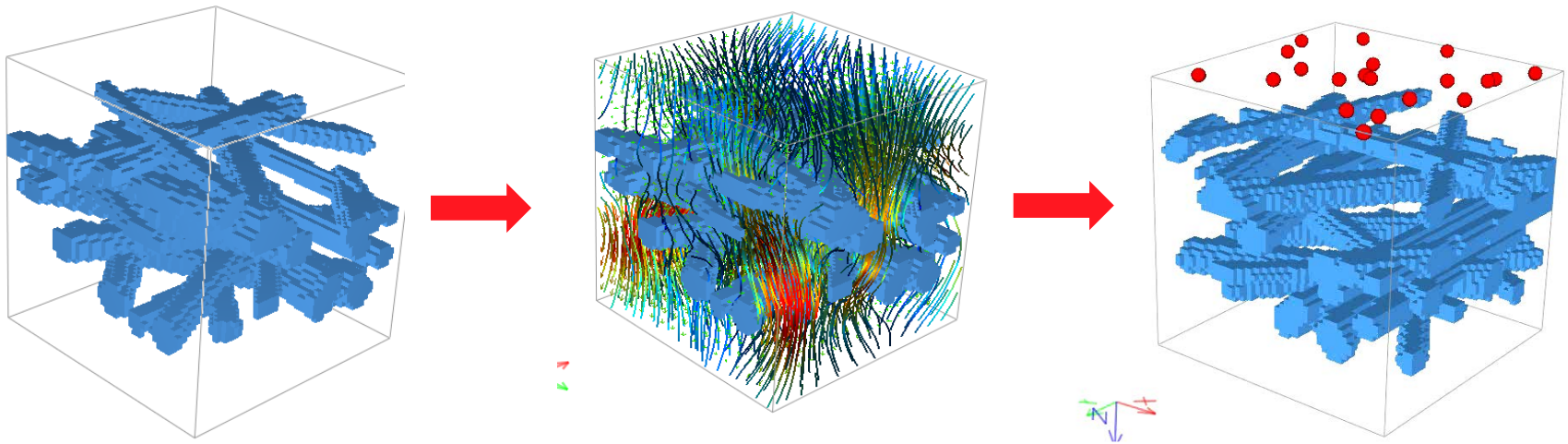
Efficiency of Clean Filter Media: Method

1. Filter media model
2. Determine flow field



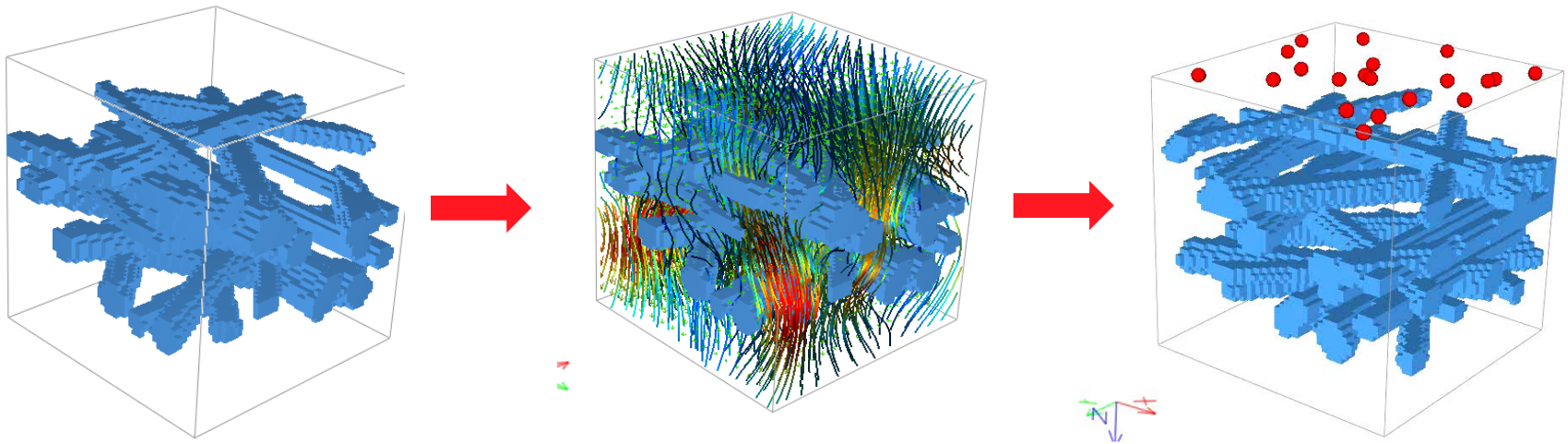
Efficiency of Clean Filter Media: Method

1. Filter media model
2. Determine flow field
3. Track particles (filtered or not?)



Efficiency of Clean Filter Media: Method

1. Filter media model
2. Determine flow field
3. Track particles (filtered or not?)
4. Result: percentage of filtered particles of each size



Movement of Particles in a Flow Field: Balance of Forces Equation

Impulse

Stokes Drag

Electrostatic
Force

$$m \frac{d\vec{v}}{dt} = 6\pi\mu \frac{R}{C_c} \left(\vec{u} - \vec{v} + \sqrt{2D} \frac{d\vec{W}(t)}{dt} \right) + Q\vec{E}$$

\vec{v} : particle velocity [m/s]

\vec{u} : fluid velocity [m/s]

R : particle radius [m]

C_c : Cunningham correction

m : particle mass [kg]

μ : dynamic viscosity [kg/m·s]

Q : particle charge [C]

E : electric field [V/m]

D : Diffusivity [m²/s]

$d\vec{W}$: 3D Wiener process

Movement of Particles in a Flow Field: Balance of Forces Equation

$$\begin{array}{c} \text{Impulse} \end{array} m \frac{d\vec{v}}{dt} = \begin{array}{c} \text{Stokes Drag} \end{array} 6\pi\mu \underbrace{\left(\frac{R}{C_c} \right)}_{\substack{\text{Cunningham Corrected} \\ \text{Particle Radius}}} \left(\vec{u} - \vec{v} + \sqrt{2D} \frac{d\vec{W}(t)}{dt} \right) + \begin{array}{c} \text{Electrostatic} \\ \text{Force} \end{array} Q\vec{E}$$

\vec{v}	: particle velocity [m/s]	μ	: dynamic viscosity [kg/m·s]
\vec{u}	: fluid velocity [m/s]	Q	: particle charge [C]
R	: particle radius [m]	E	: electric field [V/m]
C_c	: Cunningham correction	D	: Diffusivity [m ² /s]
m	: particle mass [kg]	$d\vec{W}$: 3D Wiener process

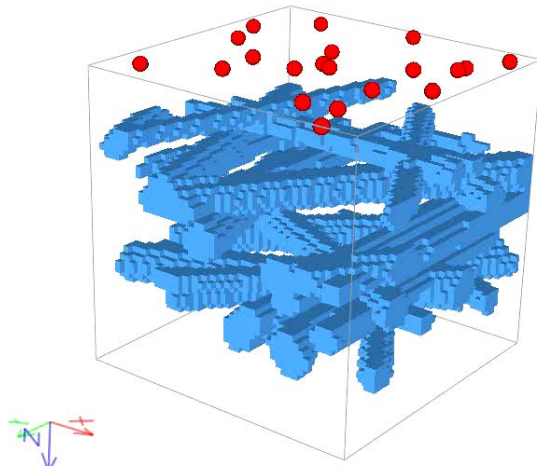
Movement of Particles in a Flow Field: Balance of Forces Equation

$$\begin{array}{c} \text{Impulse} \end{array} m \frac{d\vec{v}}{dt} = \begin{array}{c} \text{Stokes Drag} \end{array} 6\pi\mu \underbrace{\left(\frac{R}{C_c} \right)}_{\substack{\text{Cunningham Corrected} \\ \text{Particle Radius}}} \left(\vec{u} - \vec{v} + \underbrace{\sqrt{2D} \frac{d\vec{W}(t)}{dt}}_{\text{Brownian Motion}} \right) + \begin{array}{c} \text{Electrostatic} \\ \text{Force} \end{array} Q\vec{E}$$

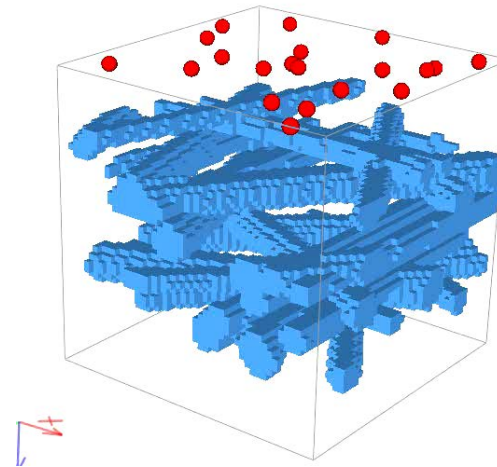
\vec{v}	: particle velocity [m/s]	μ	: dynamic viscosity [kg/m·s]
\vec{u}	: fluid velocity [m/s]	Q	: particle charge [C]
R	: particle radius [m]	E	: electric field [V/m]
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Particle Adhesion Models

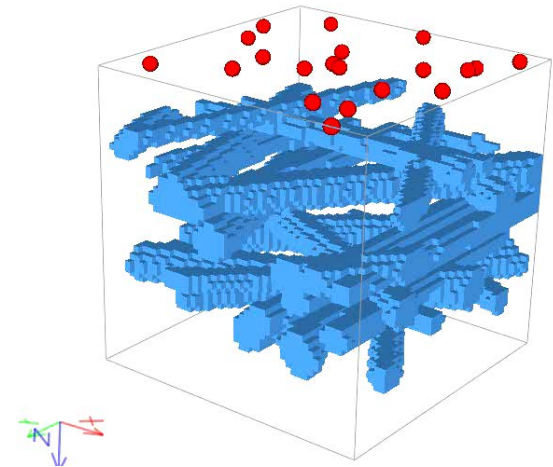
What happens when a particle touches a fiber?



Caught on first touch



Compare Kinetic and
Adhesive Forces

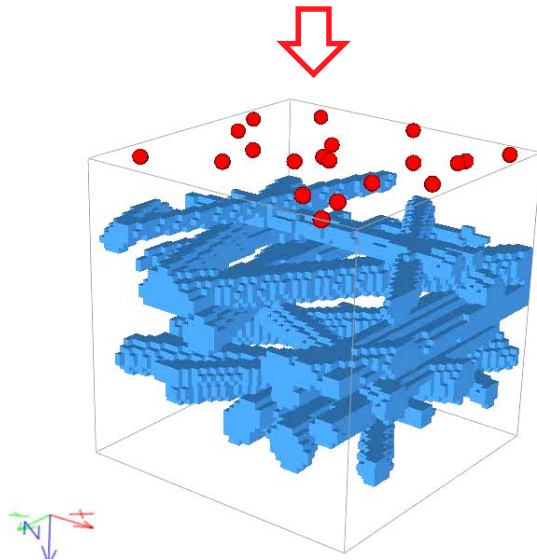


Sieving

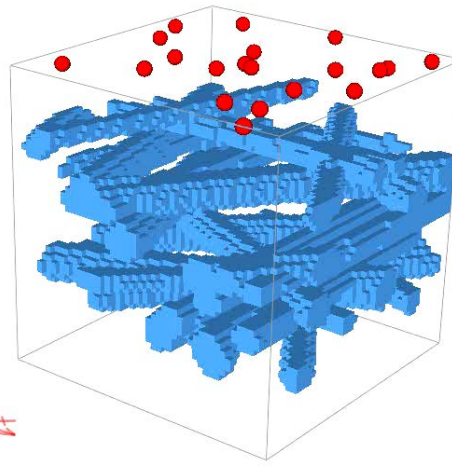
Particle Adhesion Models

What happens when a particle touches a fiber?

Air Filtration

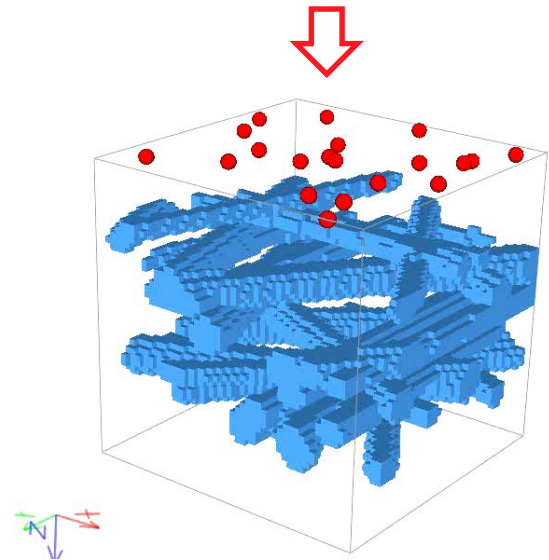


Caught on first touch



Compare Kinetic and
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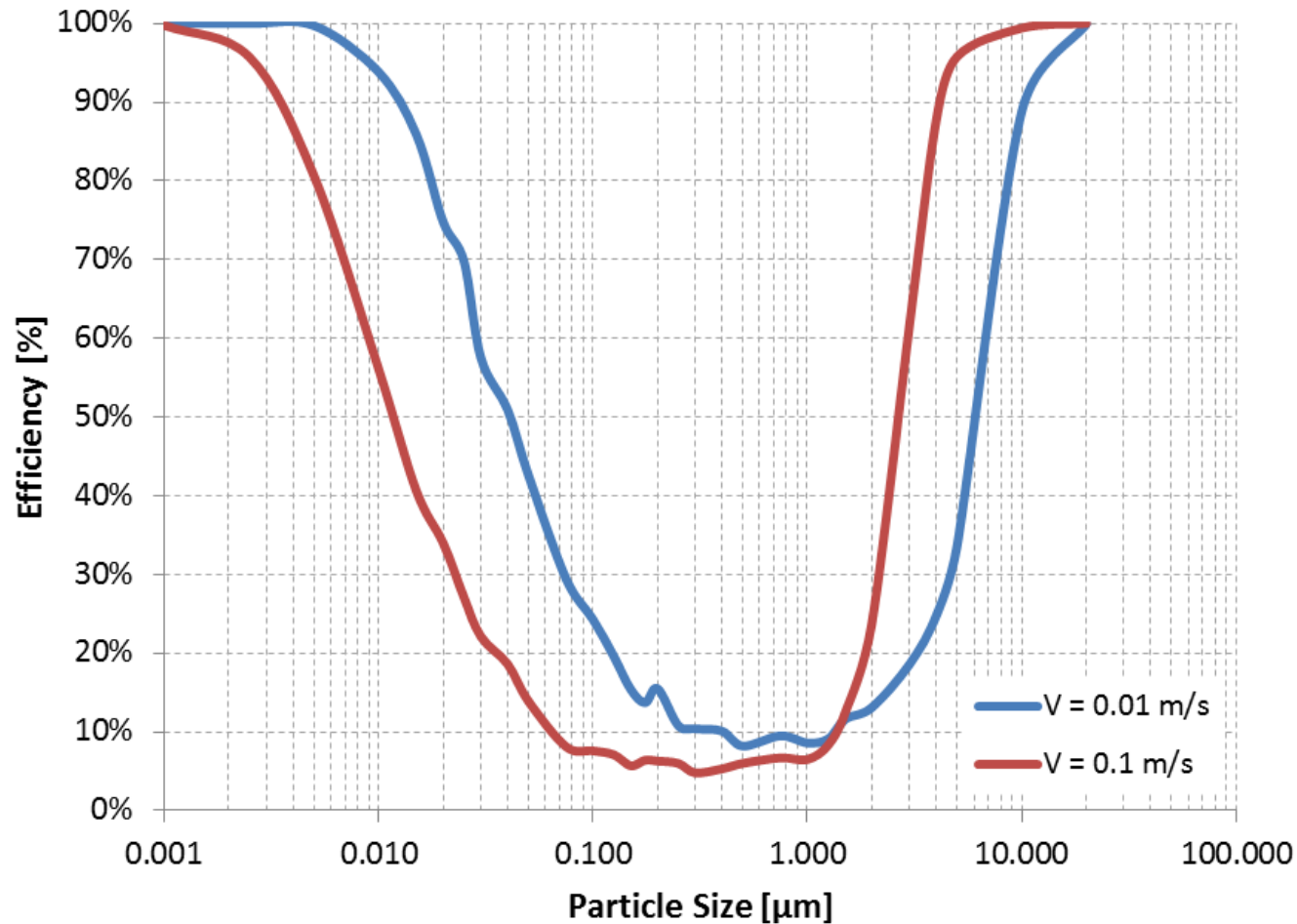
Oil Filtration



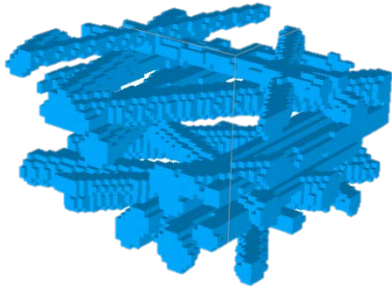
Sieving

Cabin Air Filter

Fractional Efficiency (w/o Electrostatic Attraction)

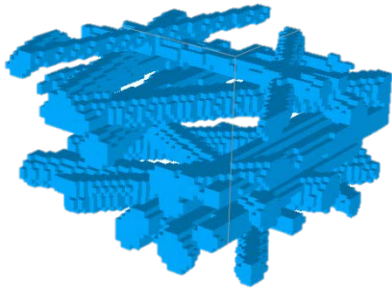


Filter Life Time Simulation - Method

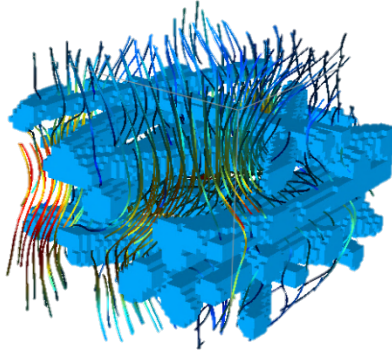


1. Filter Model

Filter Life Time Simulation - Method

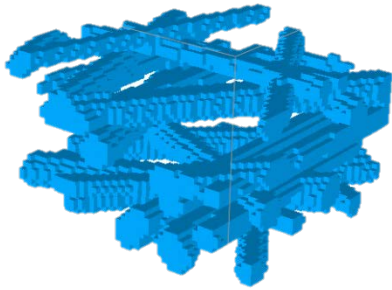


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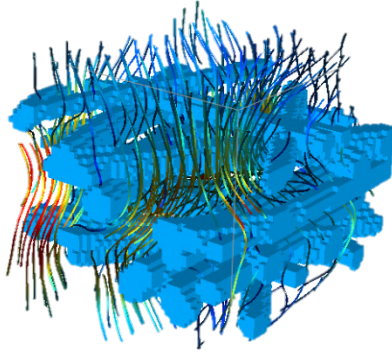


2. Flow Field

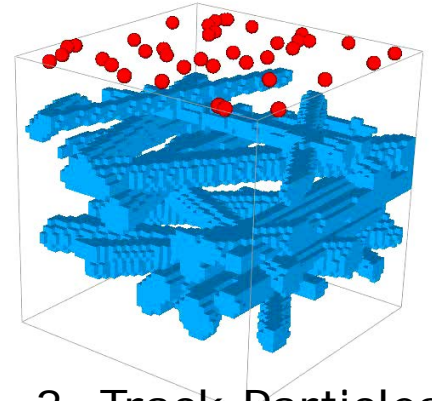
Filter Life Time Simulation - Method



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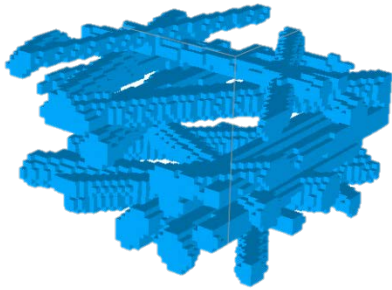


2. Flow Field

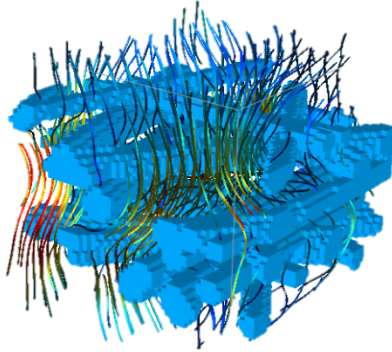


3. Track Particles

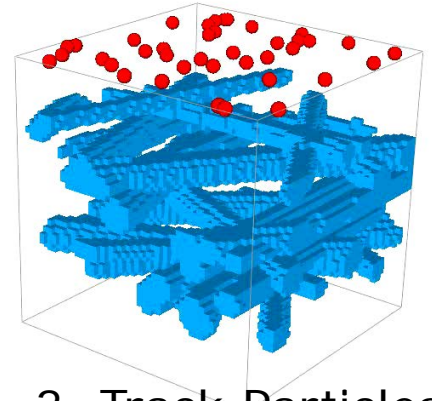
Filter Life Time Simulation - Method



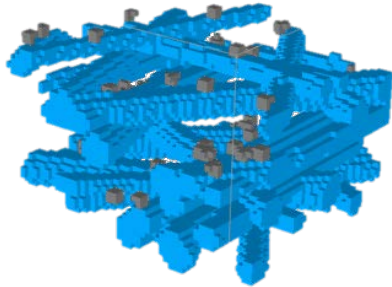
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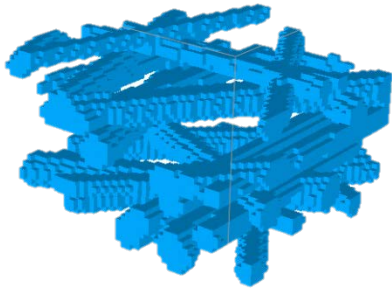


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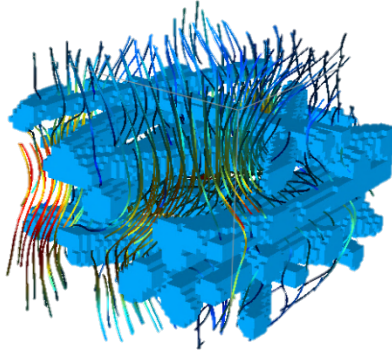


4. Deposit Particles

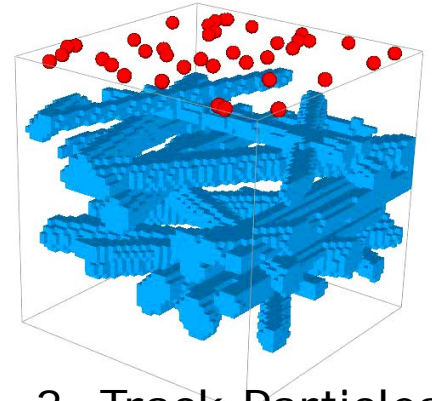
Filter Life Time Simulation - Method



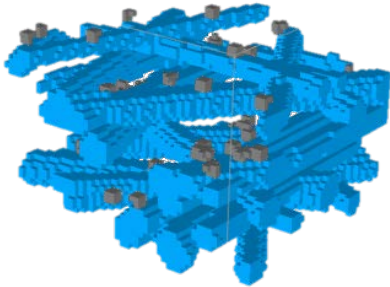
1. Filter Model



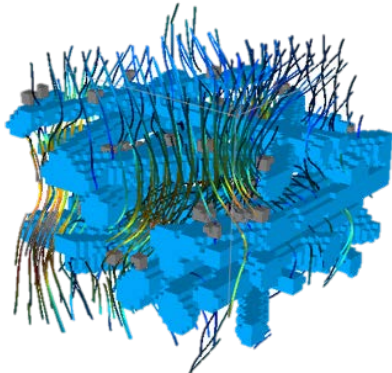
2. Flow Field



3. Track Particles

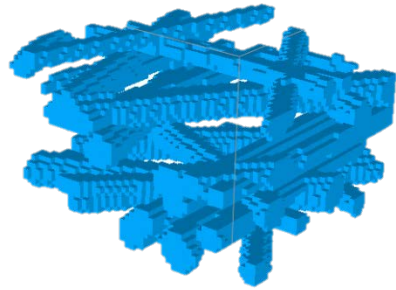


4. Deposit Particles

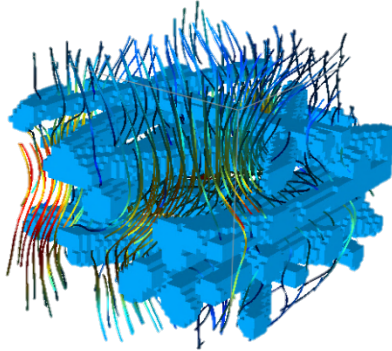


5. Recompute Flow

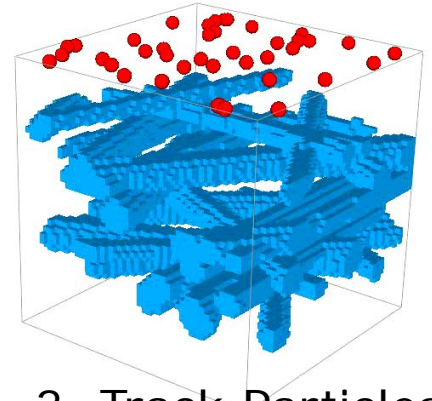
Filter Life Time Simulation - Method



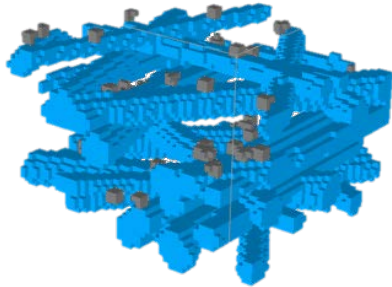
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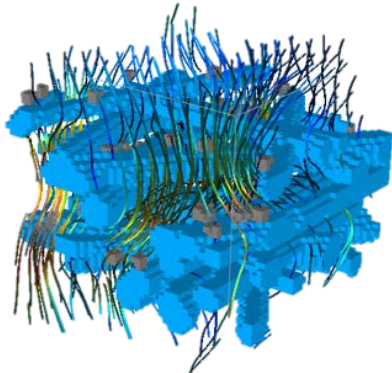
2. Flow Field



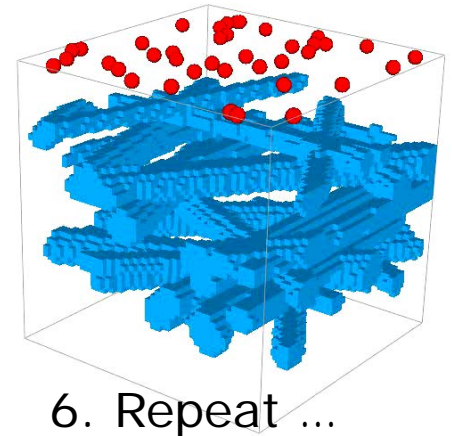
3. Track Particles



4. Deposit Particles



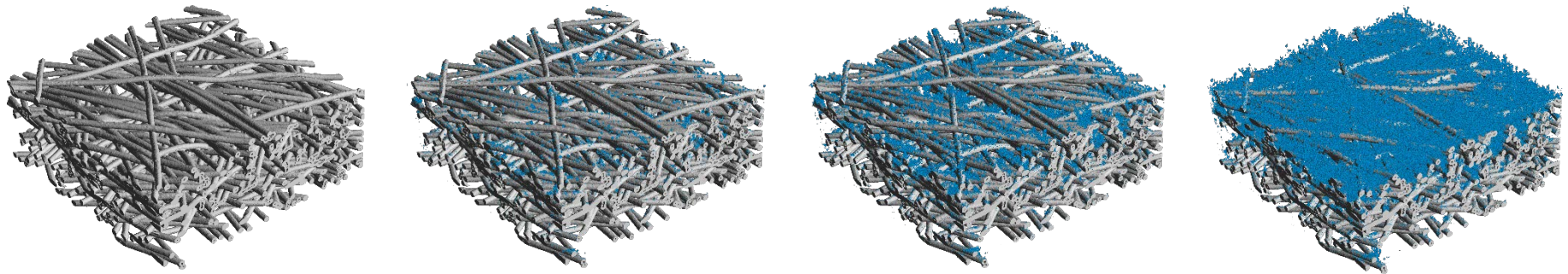
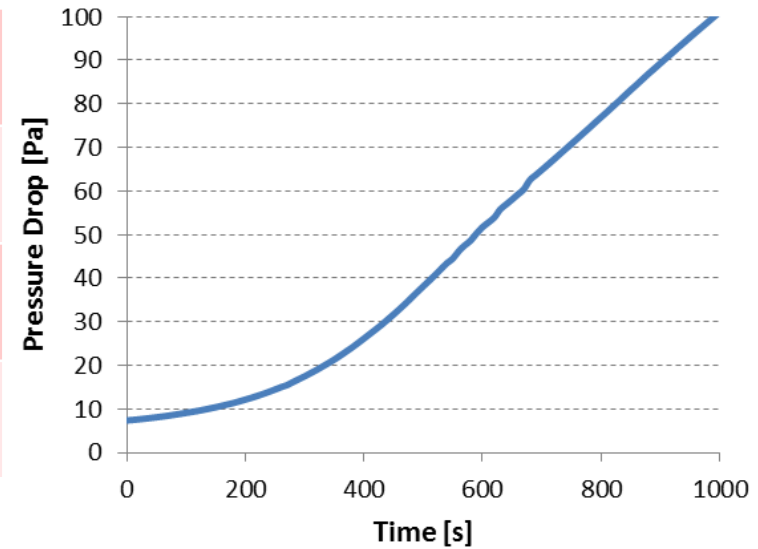
5. Recompute Flow



6. Repeat ...

Cabin Air Filter - Life Time Simulation

Initial pressure drop	7 Pa
Pressure drop after 1000s	101 Pa
Total deposited dust after 1000s	93 g/m ²
Total filter efficiency	93% (weight)



Step 2:

Create a model of the existing material

Creating a filter model

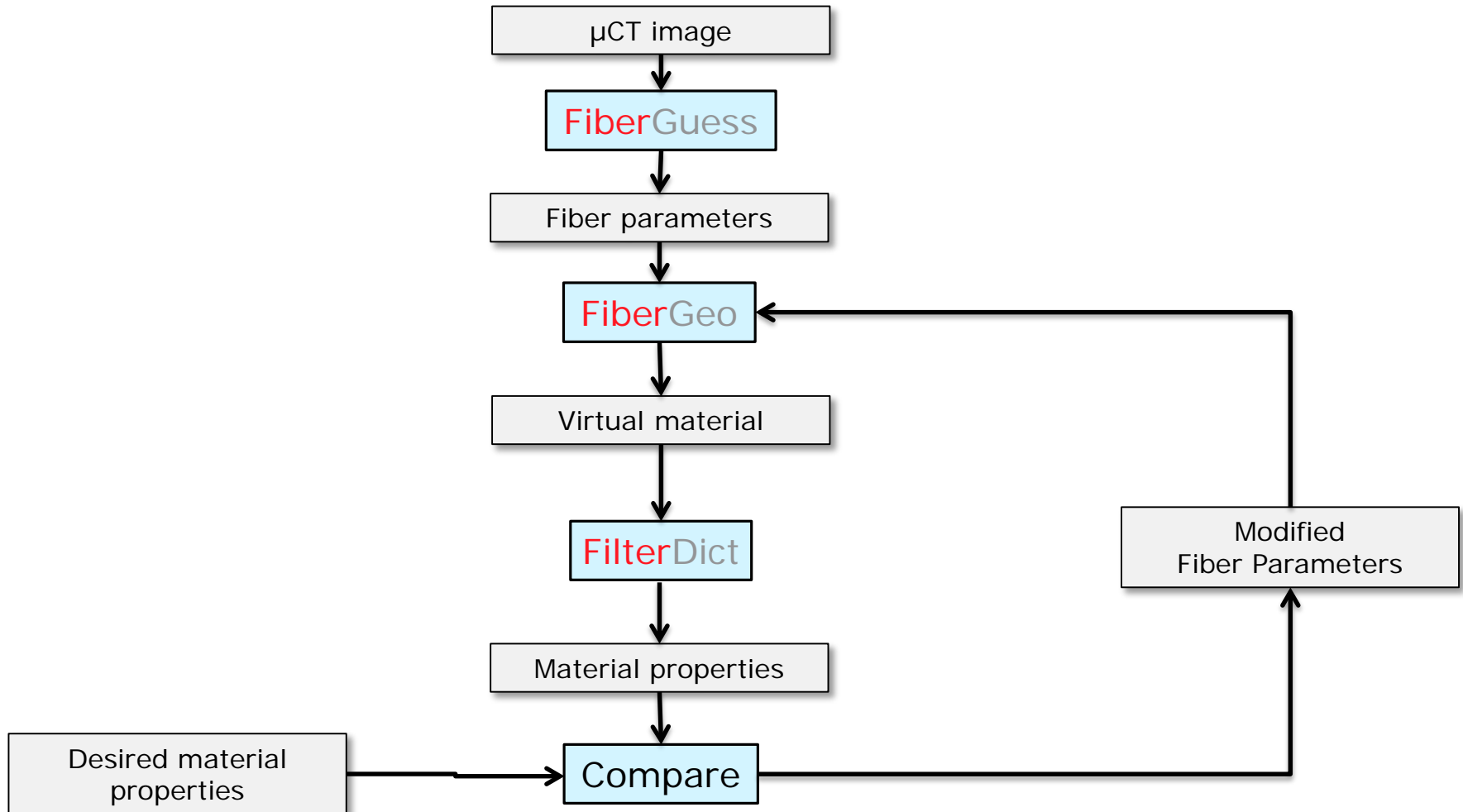
Why create a filter model?

- A CT scan is an image!
 - It can only be changed voxel-by-voxel.
 - It is not possible to remove a fiber
 - It is not possible to change diameters or shape

=> We need to “understand” the image!

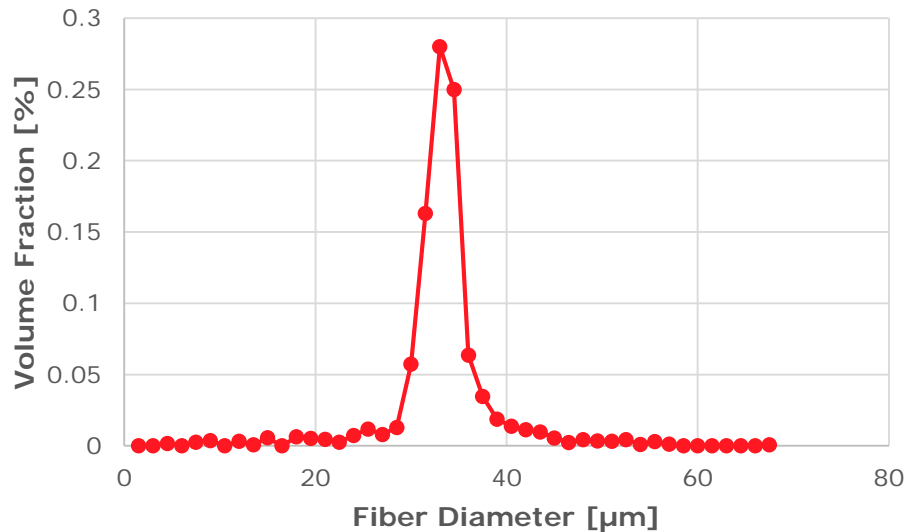


GeoDict Workflow



Geometric Analysis I:

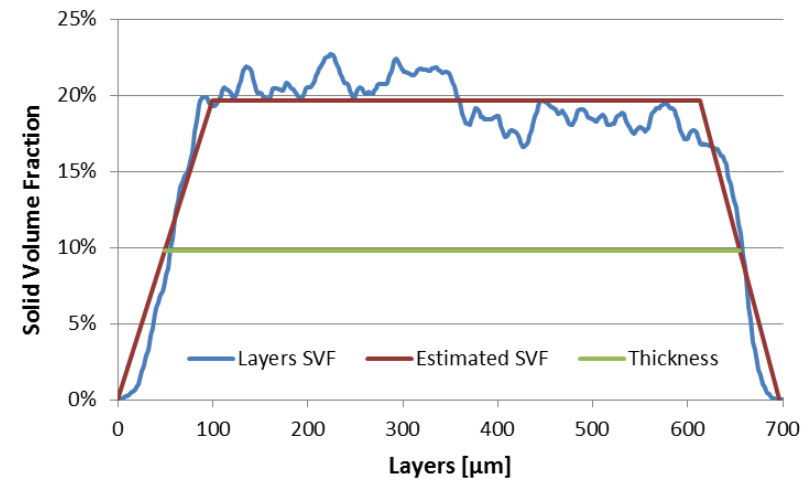
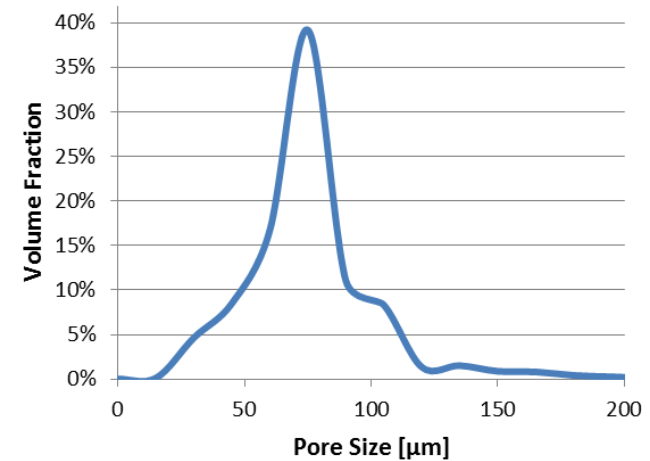
Media Thickness, Porosity, Pore Sizes, Fiber Diameter



Average fiber diameter: 33.6 μm

Porosity: 80.4 %

Thickness: 605 μm



Geometric Analysis II: Fiber Orientation

How is fiber orientation measured?



0.33	0	0
0	0.33	0
0	0	0.33



0.5	0	0
0	0.5	0
0	0	0

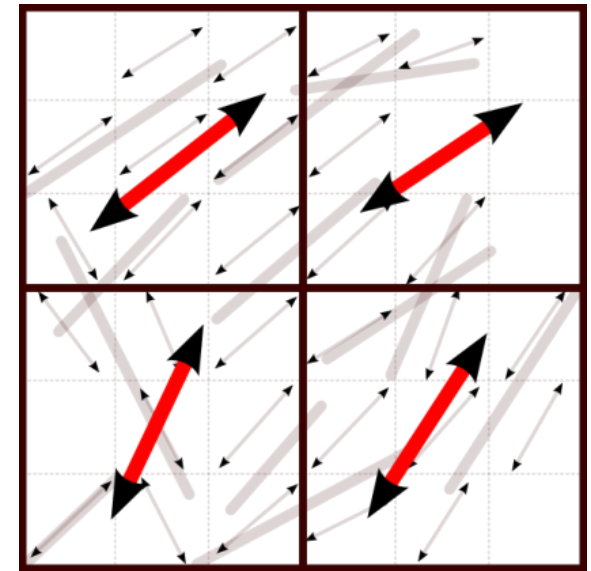
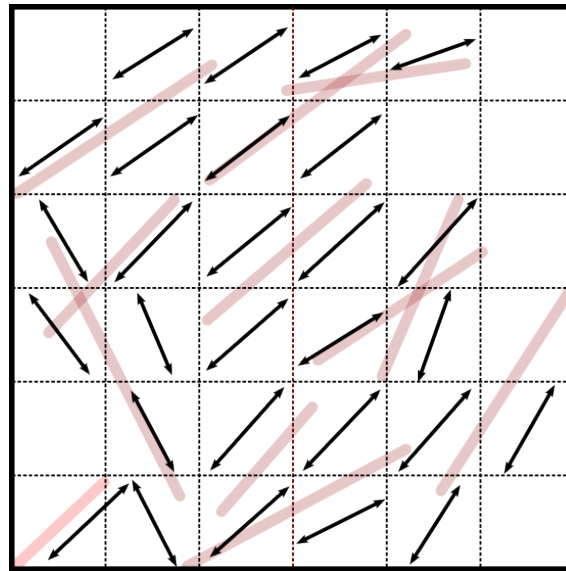
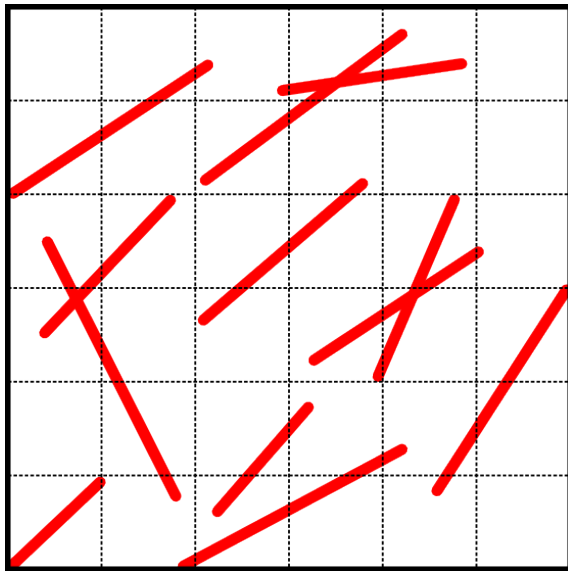


0.9	0	0
0	0.05	0
0	0	0.05

Orientation tensor describes probability of direction component.

Orientation analysis – Method 1: Principal Component Analysis (PCA)

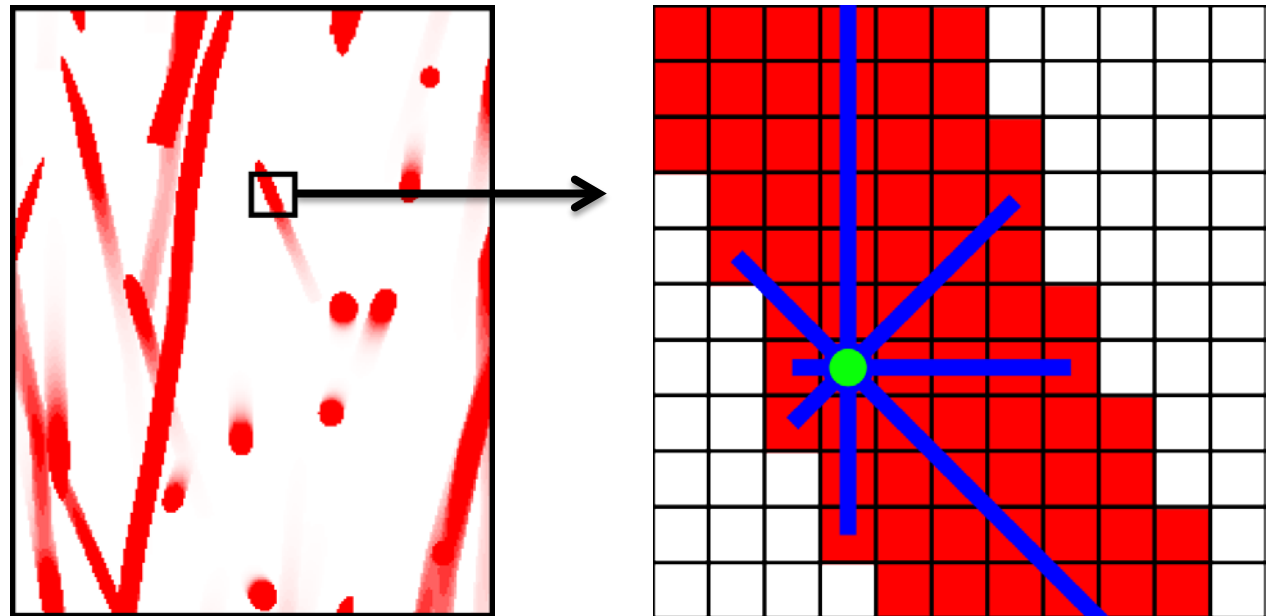
1. PCA subdivides domain into windows of given size
 - Automatic window size estimates about 2x fiber diameter
2. For each window, finds fiber fragments and analyzes direction tensor
3. For each block, averages direction tensors over windows in that block



Orientation analysis – Method 2: Star Length Distribution (SLD)

- For each voxel, SLD analyzes chord lengths through it for fixed set of directions
- The relative length of the chords gives per-voxel orientation tensor
- The tensors are averaged over all voxels in the block (similar to PCA)

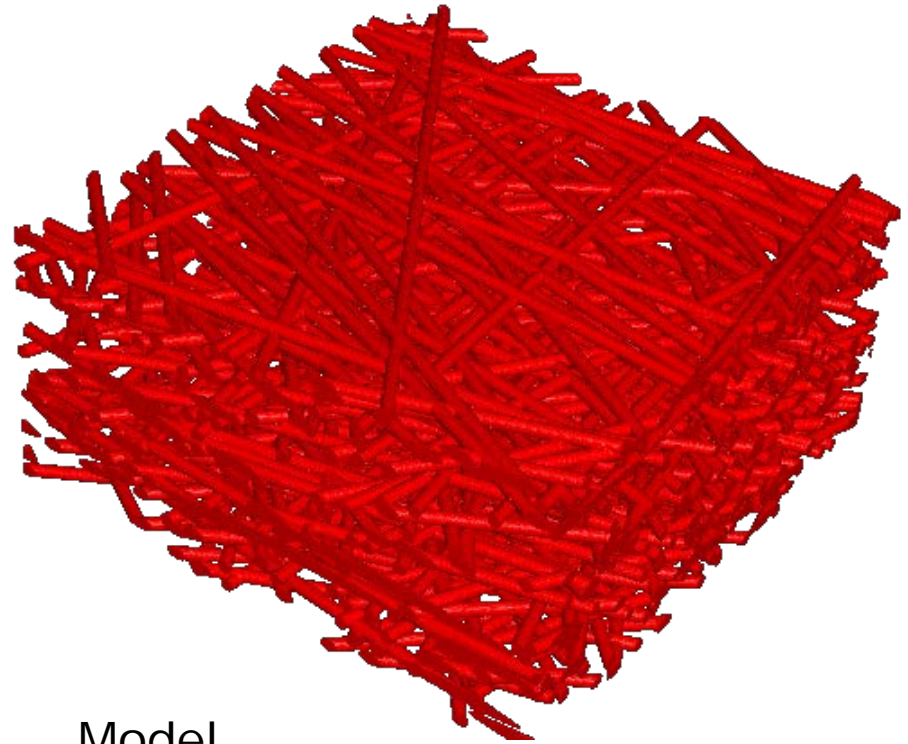
Smit, Th H., E. Schneider, and A. Odgaard. "Star length distribution: a volume-based concept for the characterization of structural anisotropy." *Journal of microscopy* 191 (1998): 249-257.



Comparison of CT Scan and Model



CT Scan



Model

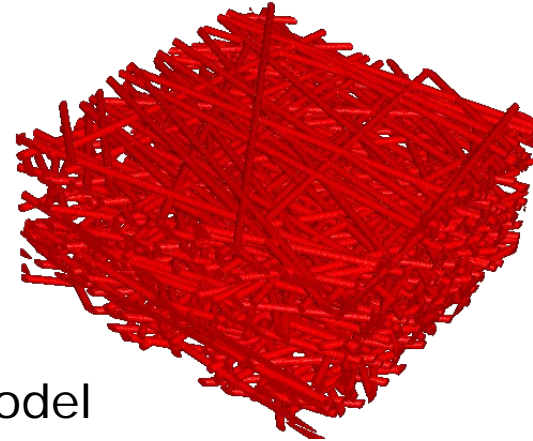
Comparison of CT Scan and Model



CT Scan

Input parameters found by CT-Scan analysis:

- media thickness
- porosity
- fiber diameter
- in-plane anisotropy

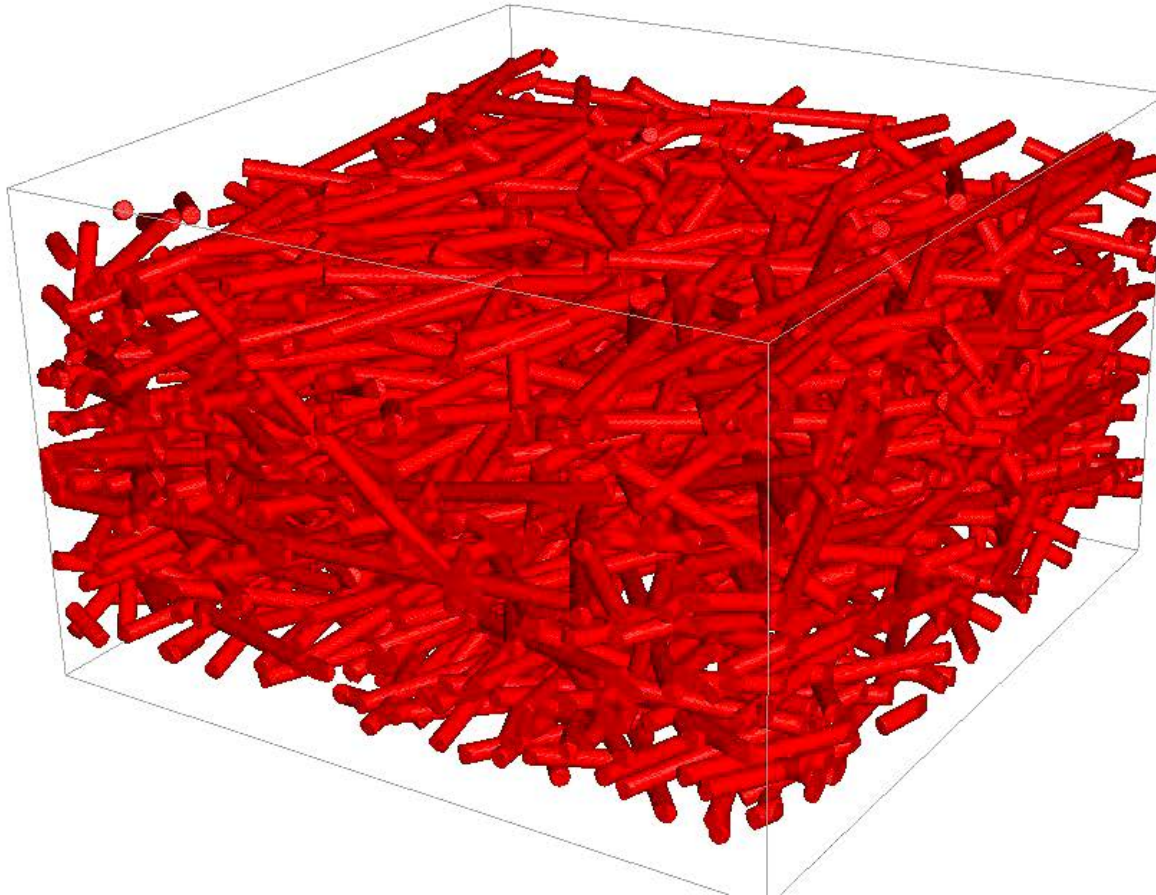


Model

Input parameters taken from assumptions:

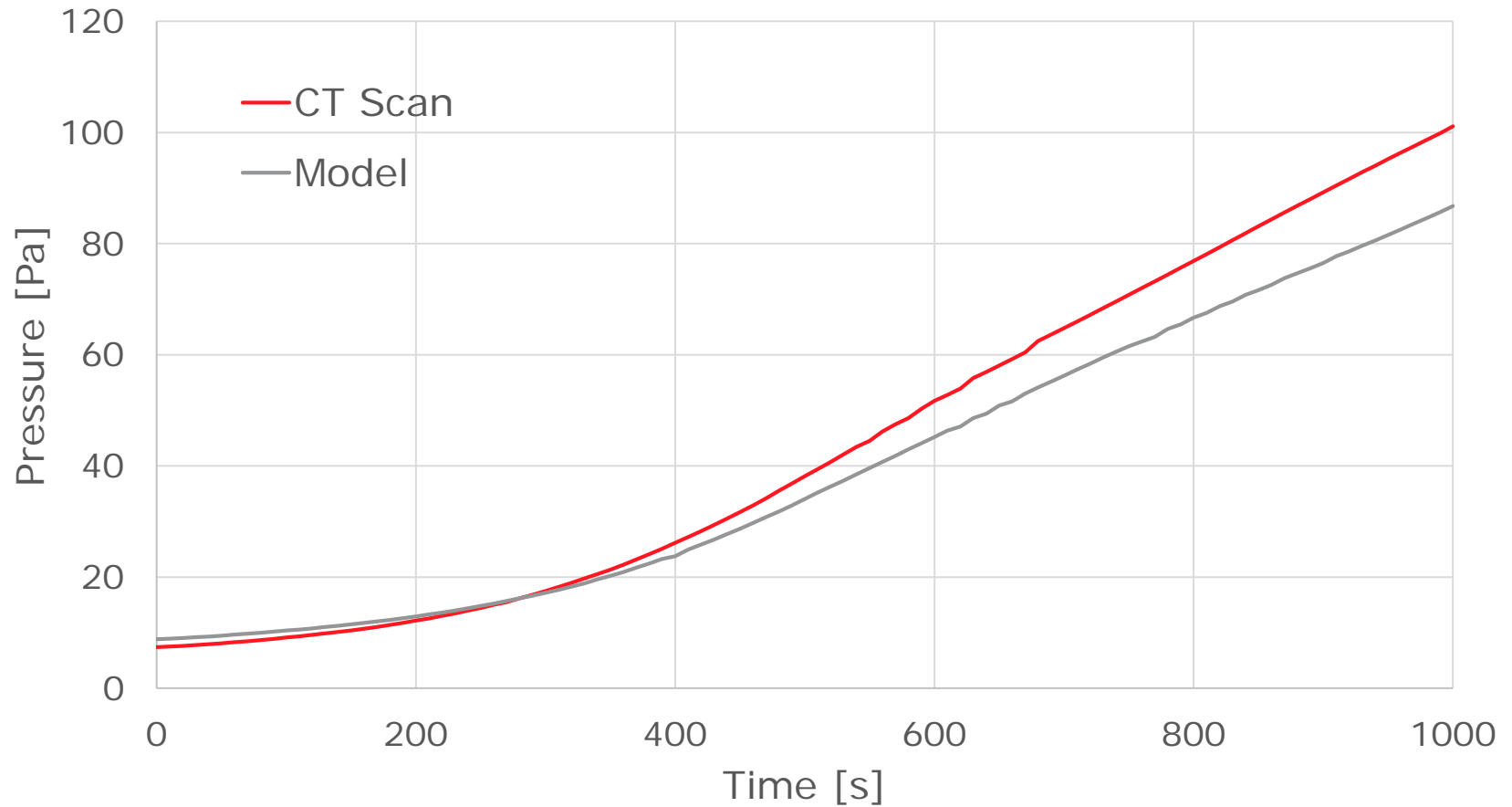
- straight fibers
- fibers oriented in-plane
- homogeneous distribution
- circular cross section

Filter Life Time



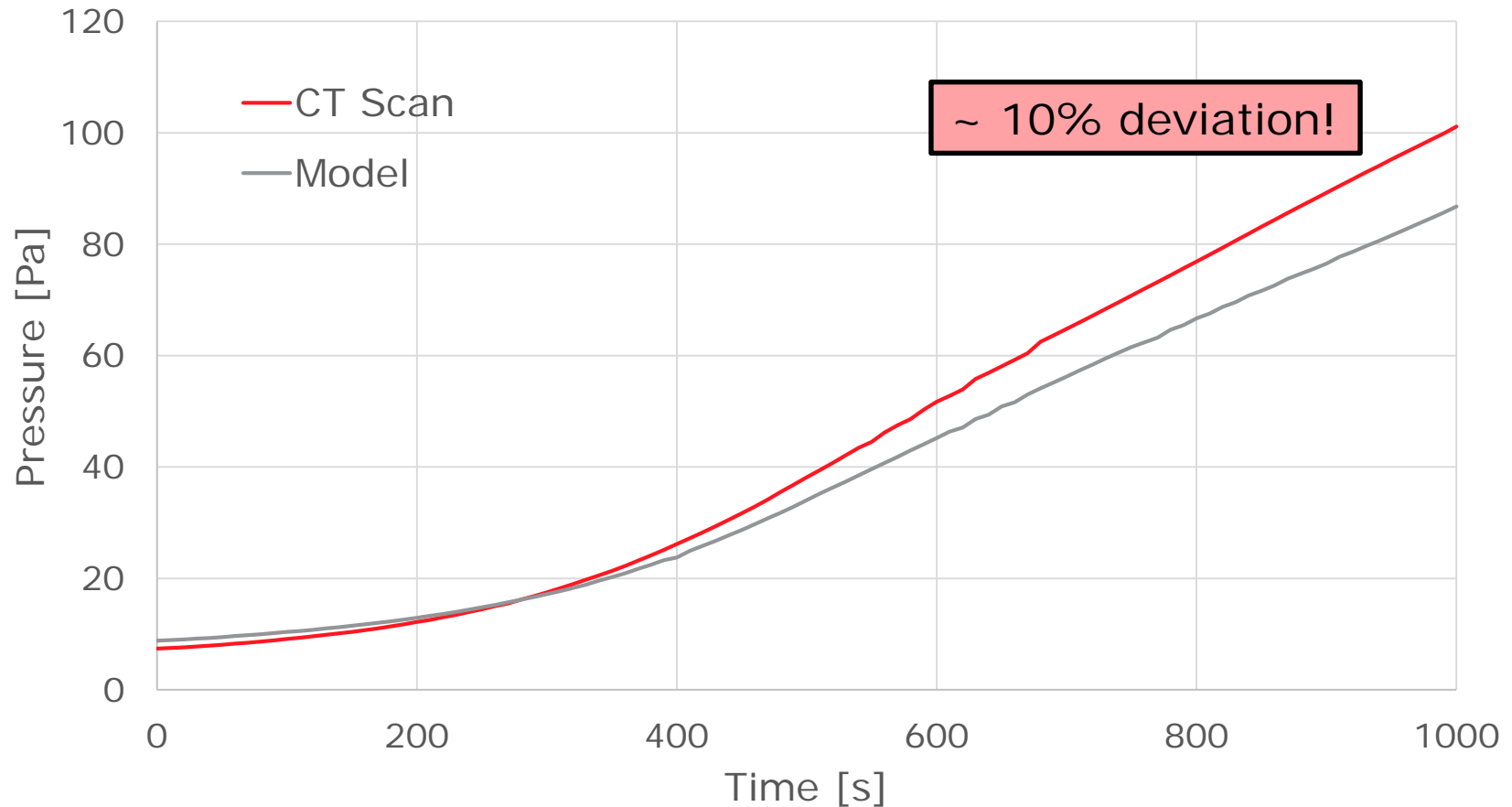
Filter Life Time Simulation

Comparison CT Scan vs Model



Filter Life Time Simulation

Comparison CT Scan vs Model

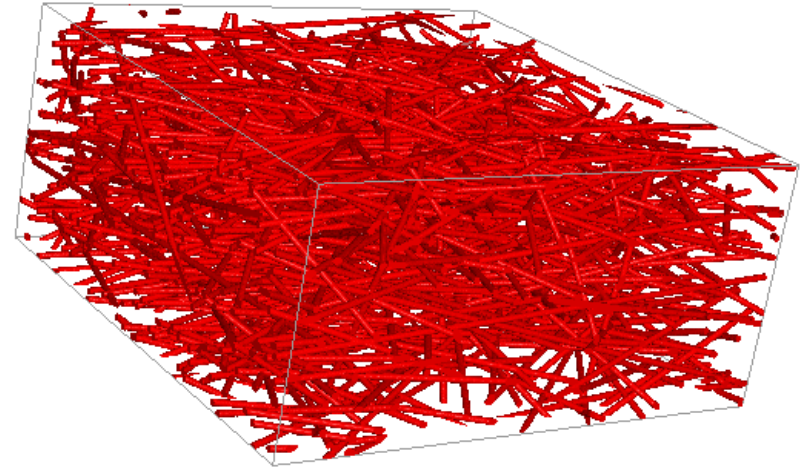
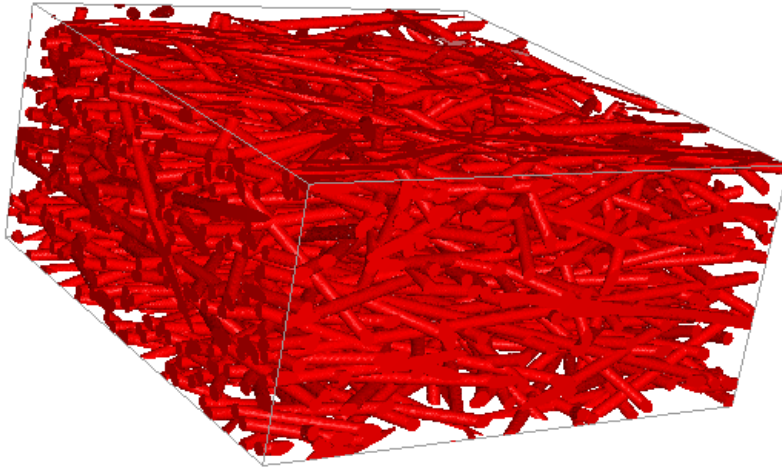


Step 3:

Modify the structure model

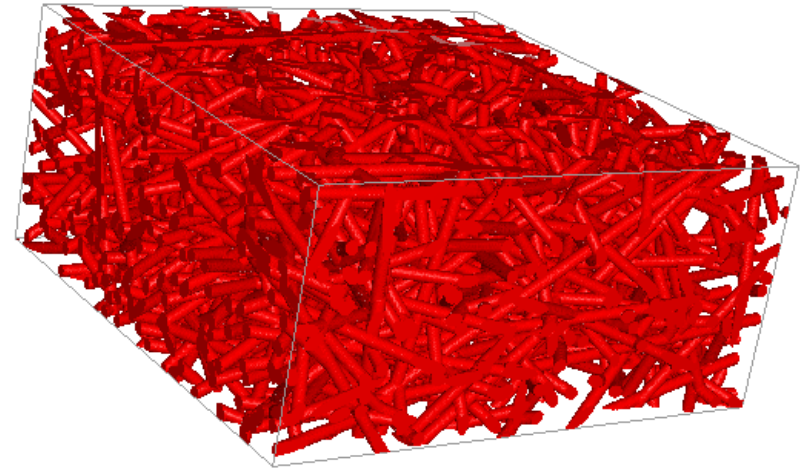
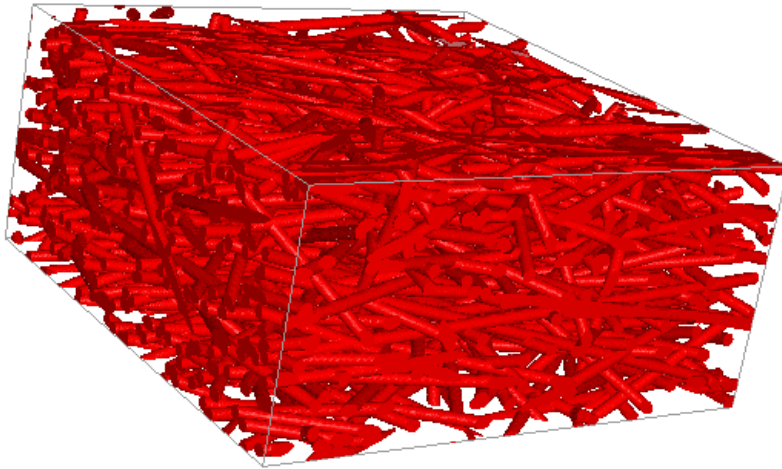
Possibilities in GeoDict to Vary the Structure Model

1. Fiber diameter



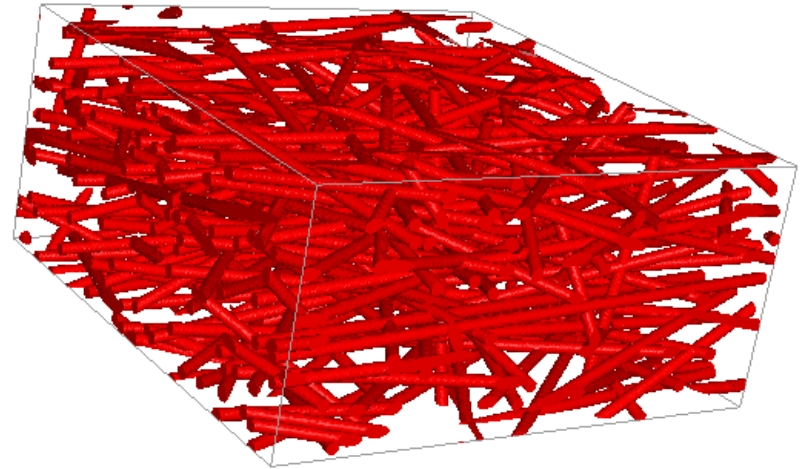
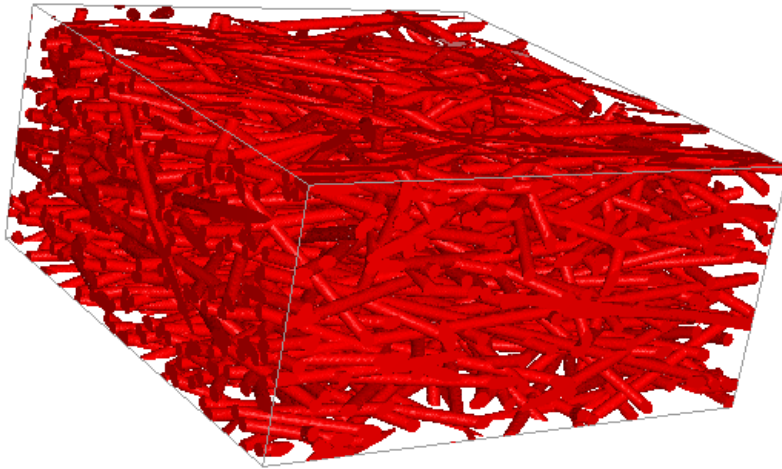
Possibilities in GeoDict to Vary the Structure Model

2. Fiber orientation



Possibilities in GeoDict to Vary the Structure Model

3. Porosity



Possibilities in GeoDict to Vary the Structure Model

4. Fiber cross sectional shape
5. Curved fibers instead of straight fibers
6. Density gradient in through-plane direction
7. Media thickness
8.

Summary and Outlook

Overall goal of this work:

- get from CT-Scan to Model structure automatically

Current state:

- works for straight fibers with circular cross section

Work in progress: curved fibers with circular cross section

- Determine curvature distribution from CT
- Realize given curvature distribution in a model

Thank You!

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