

# Analysis of Textile Filter Media and Simulation of Filtration Processes Based on $\mu$ CT Scans

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# How can simulations help to improve a filter?

Step 1: Understand the existing filter material

- CT Scan
- Simulations on CT Scan

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Step 2: Create a model of the existing material

- Analyze CT Scan
- Create structure model
- Simulations on Structure model

# How can simulations help to improve a filter?

Step 1: Understand the existing filter material

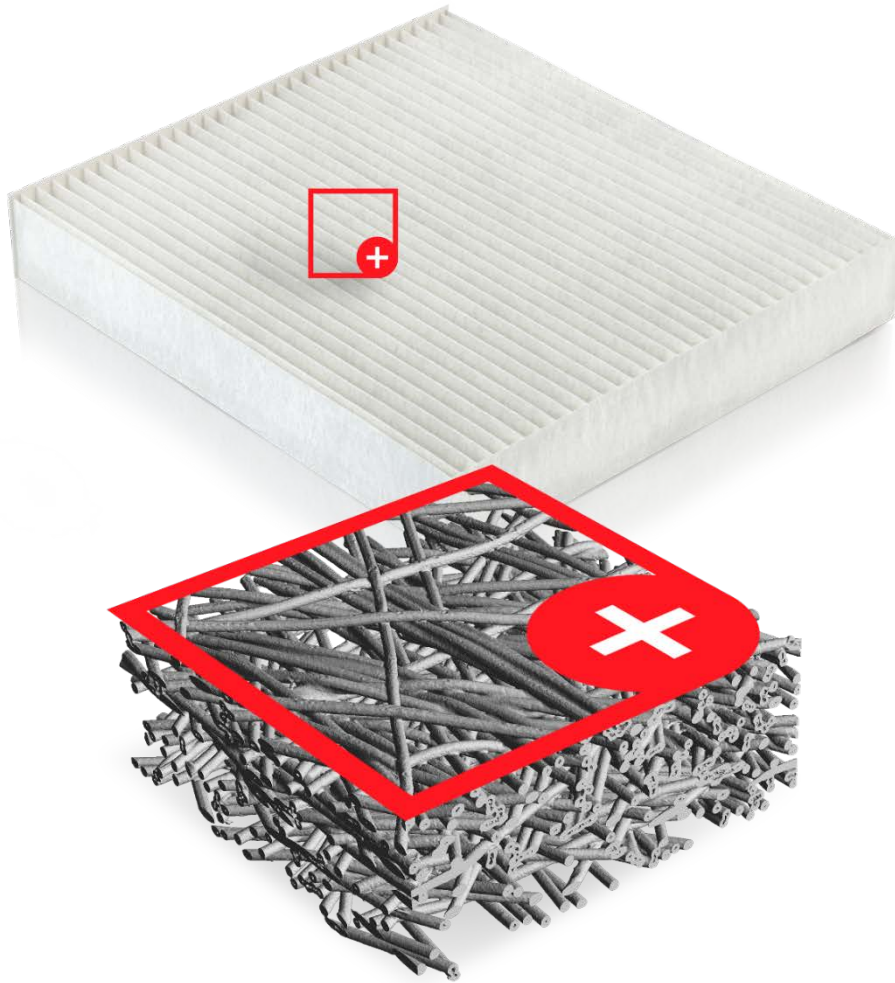
- CT Scan
- Simulations on CT Scan

Step 2: Create a model of the existing material

- Analyze CT Scan
- Create structure model
- Simulations on Structure model

Step 3: Modify the structure model

# Sample Structure: Cabin Air Filter



- Commercially available filter
- CT scan by service provider RJI Micro&Analytic

# **Step 1:**

**Understand the existing filter material**

# Determine Flow Rate or Pressure Drop

Stationary Navier-Stokes flow:

$$-\mu\Delta\vec{u} + \rho(\vec{u} \cdot \nabla)\vec{u} + \nabla p = 0$$
$$\nabla \cdot \vec{u} = 0$$

(momentum balance)

(mass conservation)

$$\vec{u} = 0 \text{ on } \Gamma$$

(no-slip on surface)

$$P_{in} = P_{out} + \text{const}$$

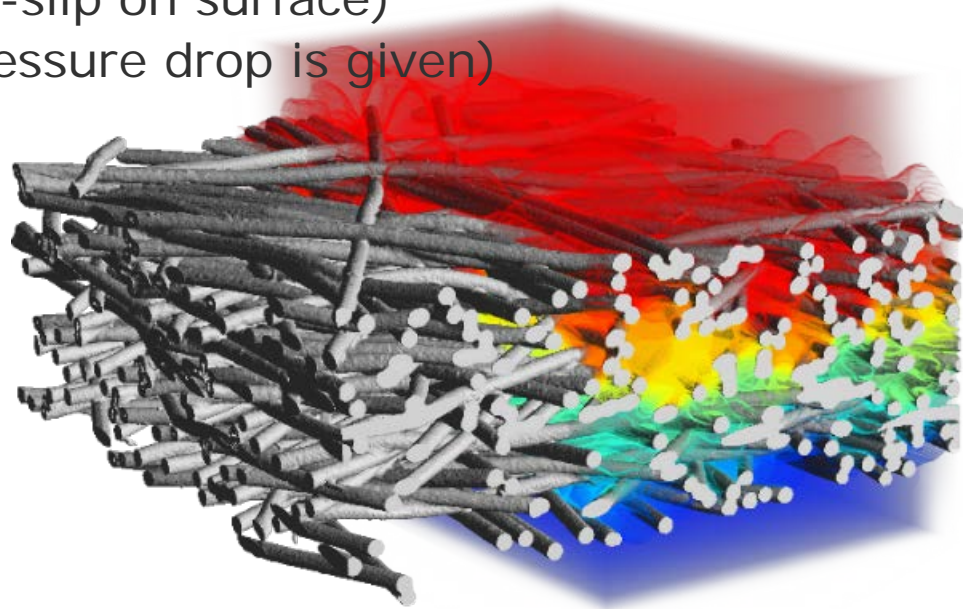
(pressure drop is given)

$\vec{u}$ : velocity

$p$ : pressure

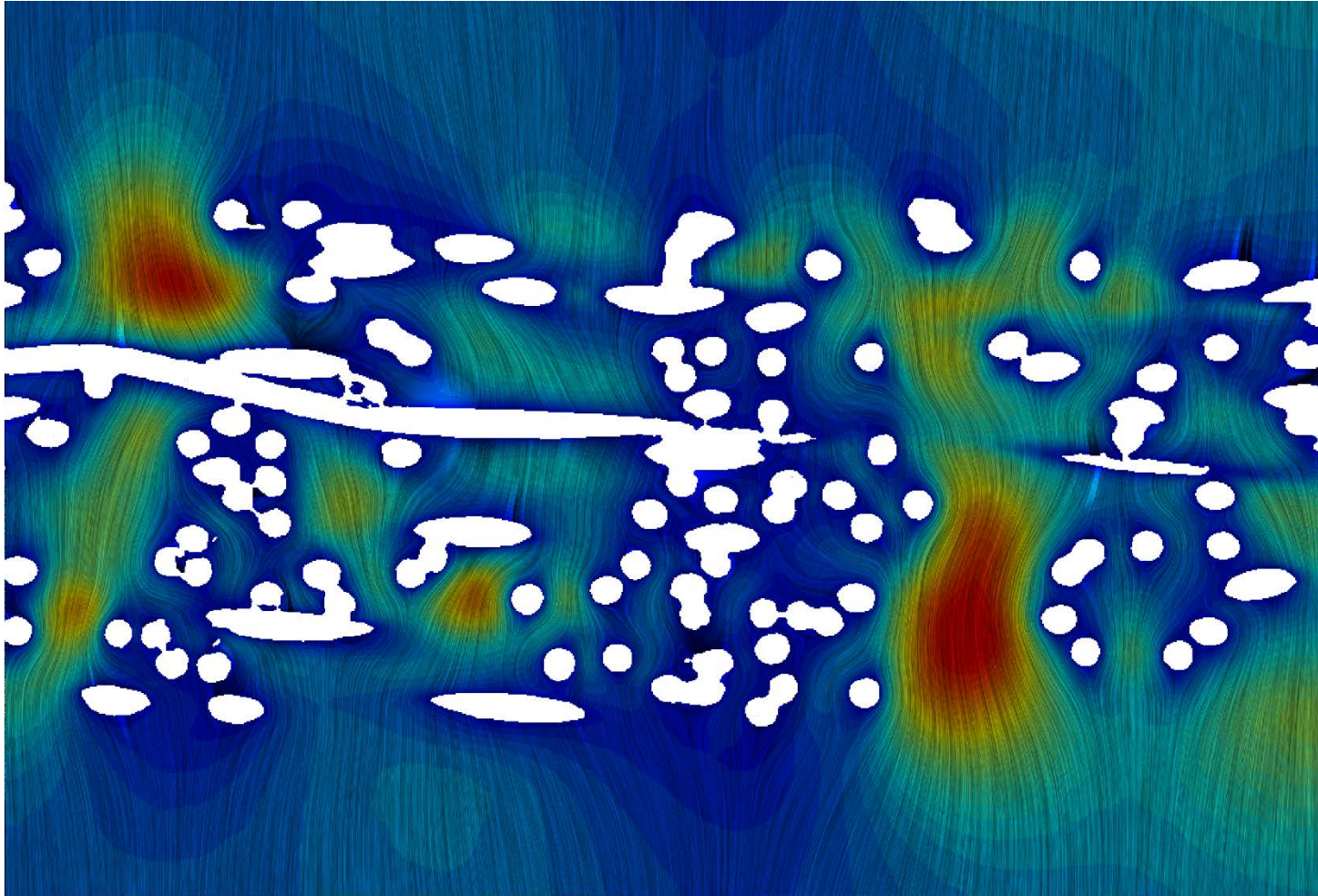
$\mu$ : dynamic viscosity

$\rho$ : fluid density





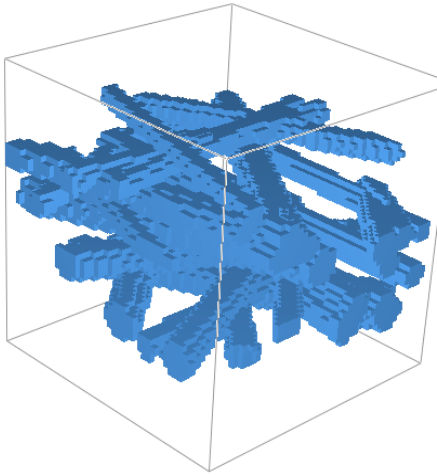
## Result for Clean Cabin Air Filter Media (Flat Sheet): Pressure drop of 7.35 Pa at 0.1 m/s mean velocity





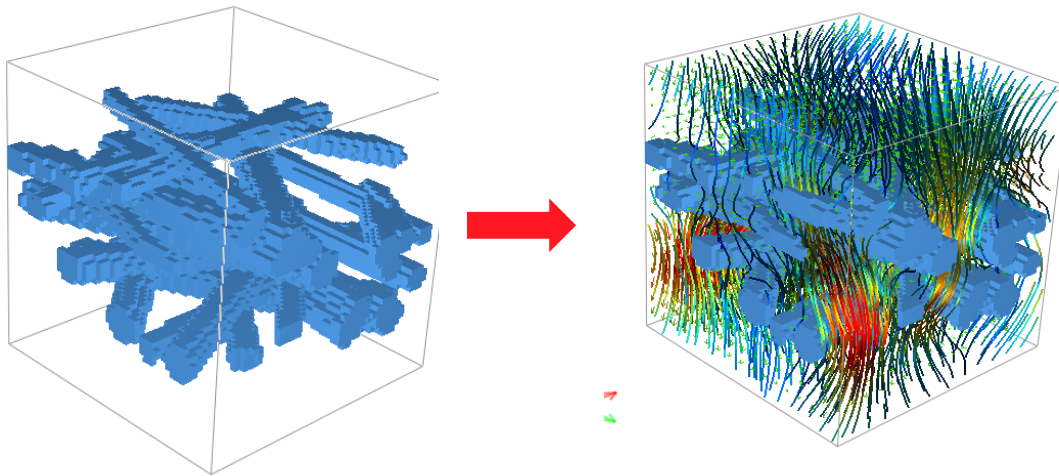
# Efficiency of Clean Filter Media: Method

## 1. Filter media model



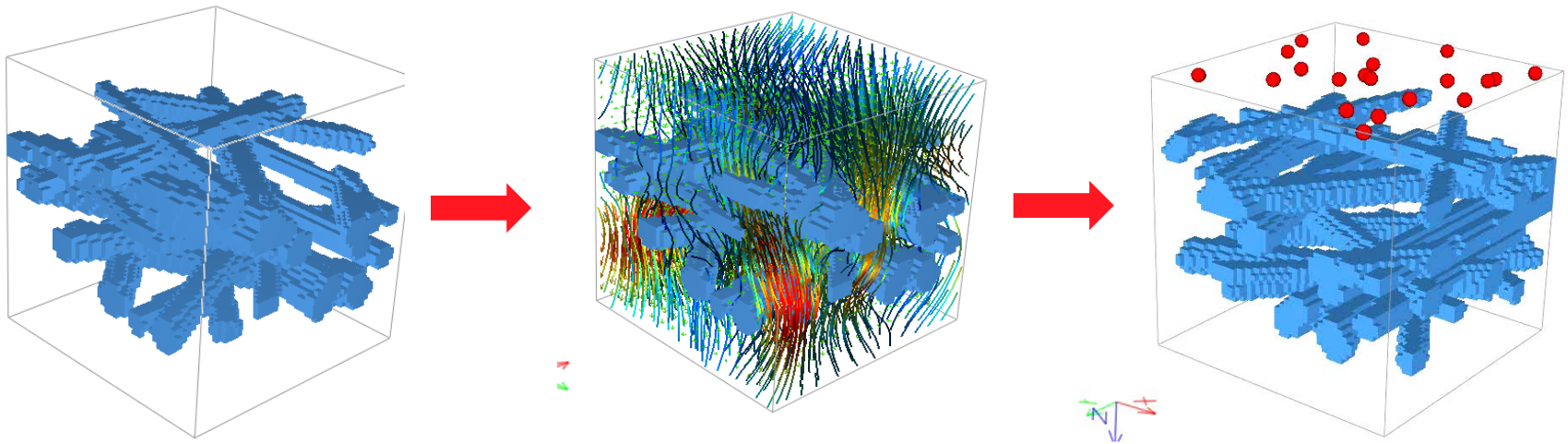
# Efficiency of Clean Filter Media: Method

1. Filter media model
2. Determine flow field



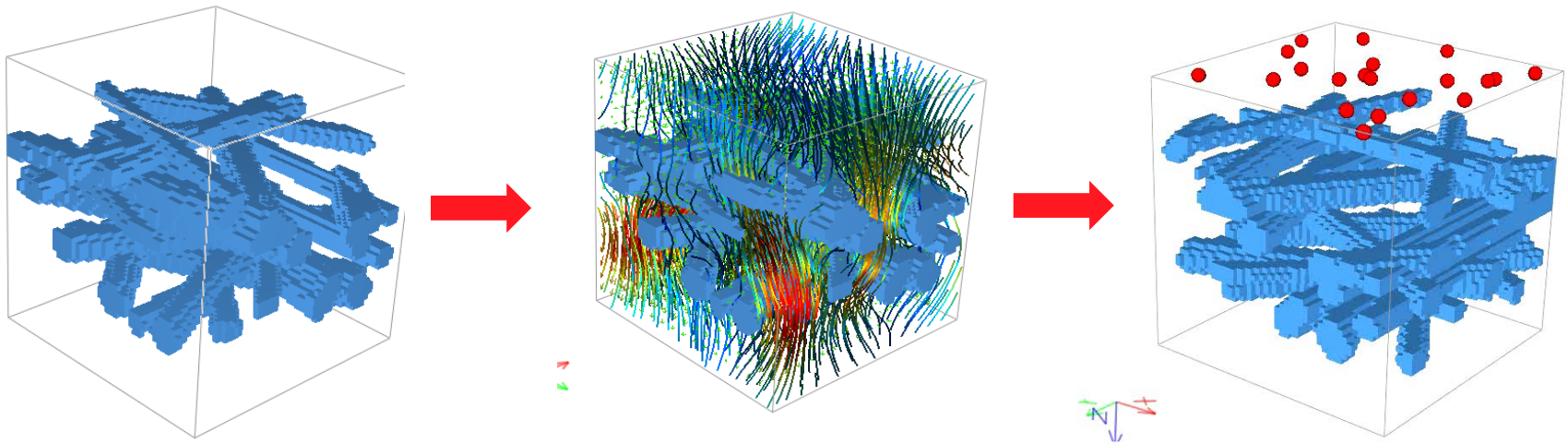
# Efficiency of Clean Filter Media: Method

1. Filter media model
2. Determine flow field
3. Track particles (filtered or not?)



# Efficiency of Clean Filter Media: Method

1. Filter media model
2. Determine flow field
3. Track particles (filtered or not?)
4. Result: percentage of filtered particles of each size



# Movement of Particles in a Flow Field: Balance of Forces Equation

Impulse

Stokes Drag

Electrostatic  
Force

$$m \frac{d\vec{v}}{dt} = 6\pi\mu \frac{R}{C_c} \left( \vec{u} - \vec{v} + \sqrt{2D} \frac{d\vec{W}(t)}{dt} \right) + Q\vec{E}$$

$\vec{v}$  : particle velocity [m/s]

$\vec{u}$  : fluid velocity [m/s]

$R$  : particle radius [m]

$C_c$  : Cunningham correction

$m$  : particle mass [kg]

$\mu$  : dynamic viscosity [kg/m·s]

$Q$  : particle charge [C]

$E$  : electric field [V/m]

$D$  : Diffusivity [m<sup>2</sup>/s]

$d\vec{W}$  : 3D Wiener process

# Movement of Particles in a Flow Field: Balance of Forces Equation

$$\begin{array}{ccc}
 \text{Impulse} & \text{Stokes Drag} & \text{Electrostatic Force} \\
 m \frac{d\vec{v}}{dt} & = 6\pi\mu \left( \frac{R}{C_c} \right) \left( \vec{u} - \vec{v} + \sqrt{2D} \frac{d\vec{W}(t)}{dt} \right) & + Q\vec{E} \\
 & \text{Cunningham Corrected} & \\
 & \text{Particle Radius} & 
 \end{array}$$

$\vec{v}$	: particle velocity [m/s]	$\mu$	: dynamic viscosity [kg/m·s]
$\vec{u}$	: fluid velocity [m/s]	$Q$	: particle charge [C]
$R$	: particle radius [m]	$E$	: electric field [V/m]
$C_c$	: Cunningham correction	$D$	: Diffusivity [m <sup>2</sup> /s]
$m$	: particle mass [kg]	$d\vec{W}$	: 3D Wiener process

# Movement of Particles in a Flow Field: Balance of Forces Equation

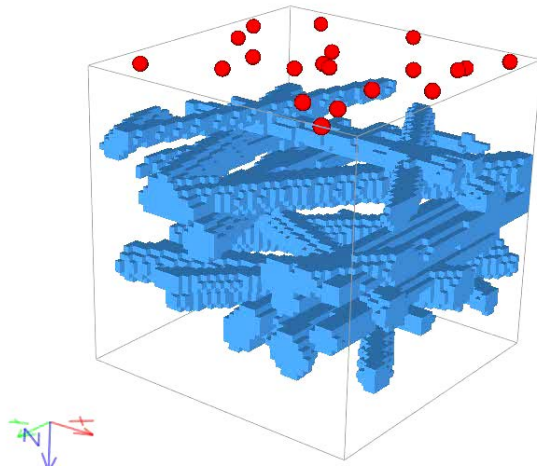
$$\begin{array}{c} \text{Impulse} \end{array} m \frac{d\vec{v}}{dt} = \begin{array}{c} \text{Stokes Drag} \end{array} 6\pi\mu \underbrace{\left( \frac{R}{C_c} \right)}_{\substack{\text{Cunningham Corrected} \\ \text{Particle Radius}}} \left( \vec{u} - \vec{v} + \underbrace{\sqrt{2D} \frac{d\vec{W}(t)}{dt}}_{\text{Brownian Motion}} \right) + \begin{array}{c} \text{Electrostatic} \\ \text{Force} \end{array} Q\vec{E}$$

$\vec{v}$	: particle velocity [m/s]	$\mu$	: dynamic viscosity [kg/m·s]
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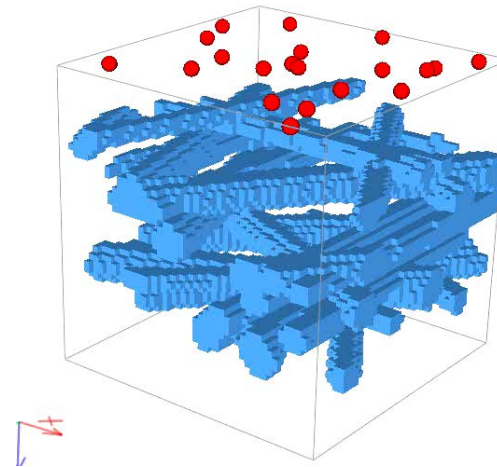


# Particle Adhesion Models

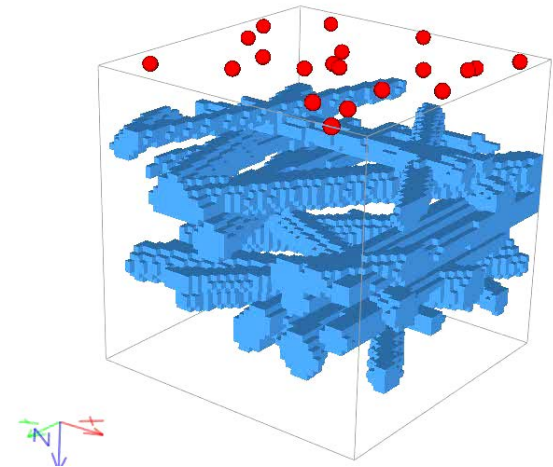
What happens when a particle touches a fiber?



Caught on first touch



Compare Kinetic and  
Adhesive Forces

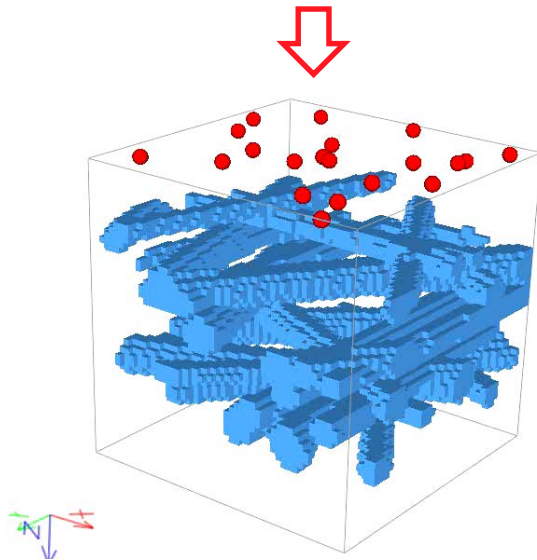


Sieving

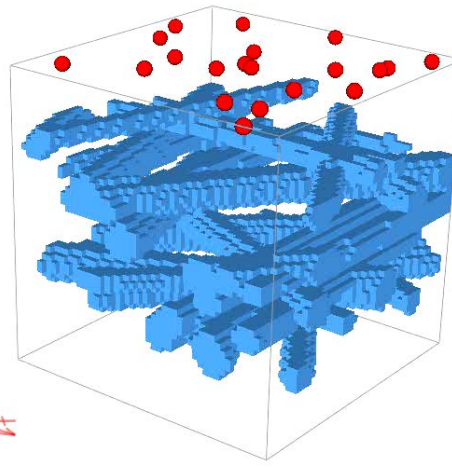
# Particle Adhesion Models

What happens when a particle touches a fiber?

Air Filtration

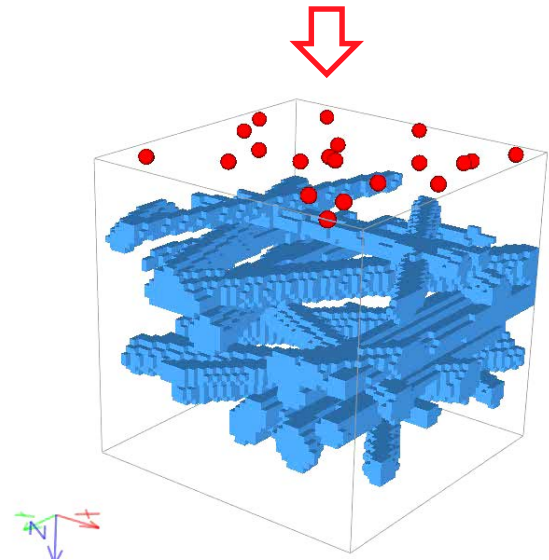


Caught on first touch



Compare Kinetic and  
Adhesive Forces

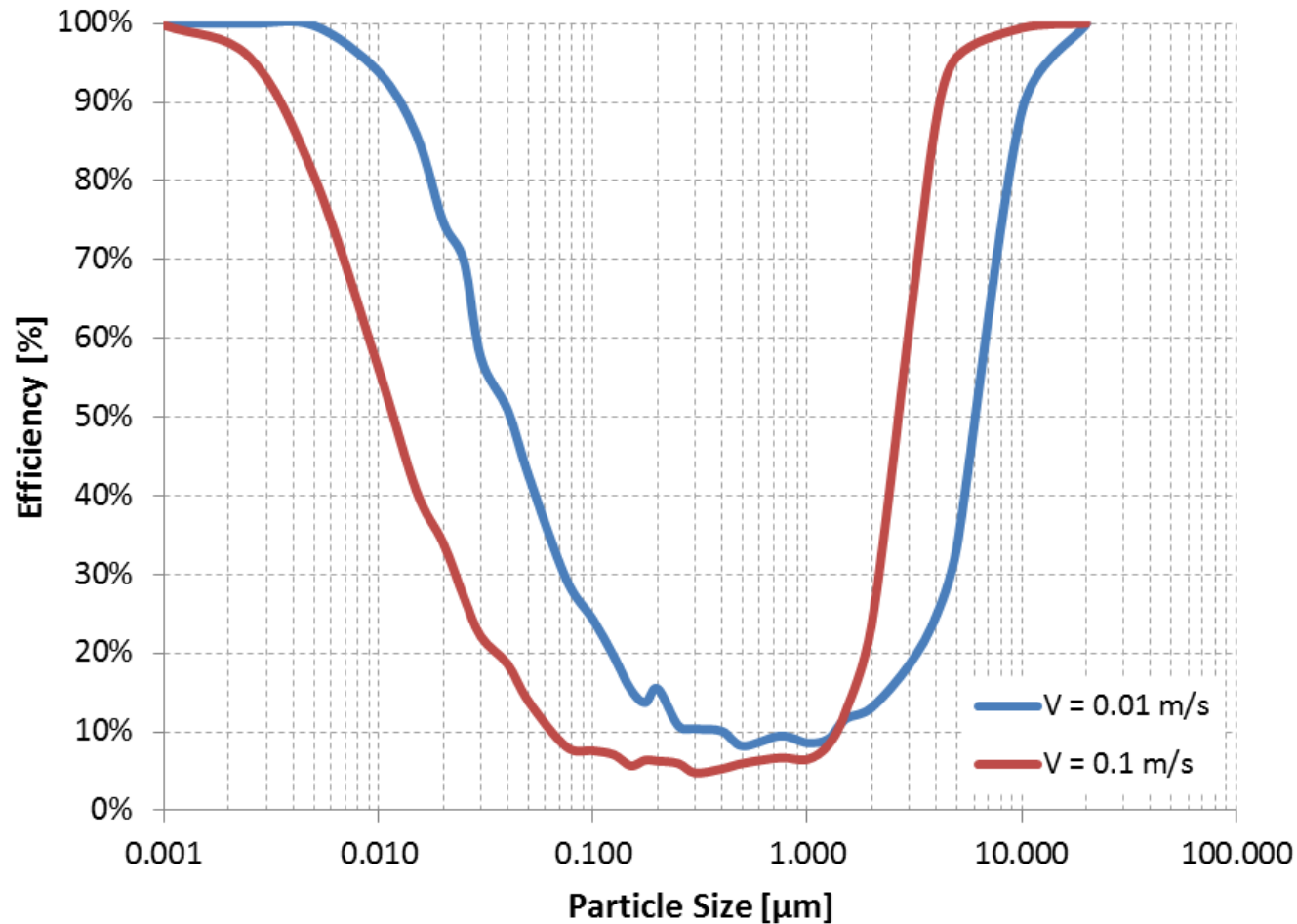
Oil Filtration



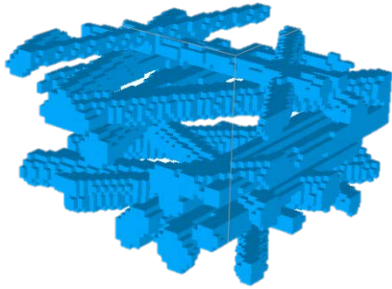
Sieving

# Cabin Air Filter

## Fractional Efficiency (w/o Electrostatic Attraction)

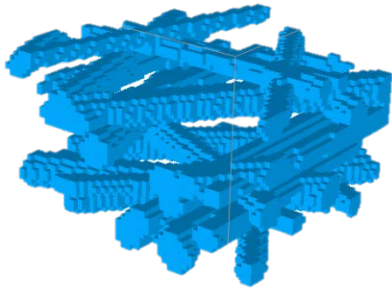


# Filter Life Time Simulation - Method

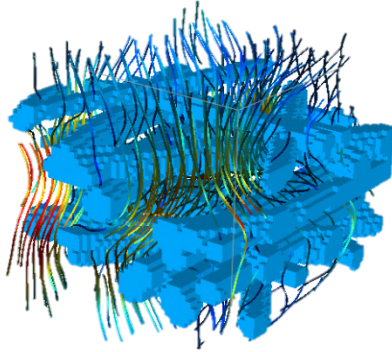


## 1. Filter Model

# Filter Life Time Simulation - Method

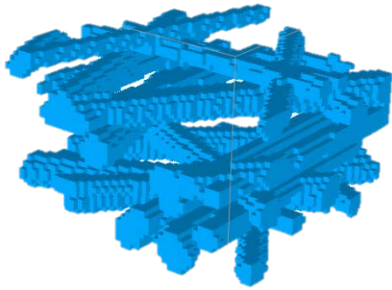


1. Filter Model

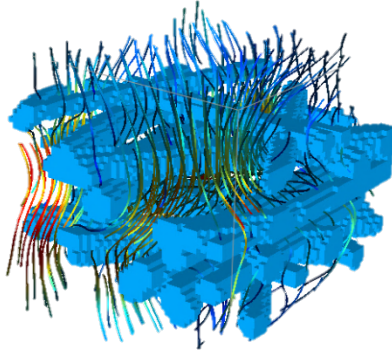


2. Flow Field

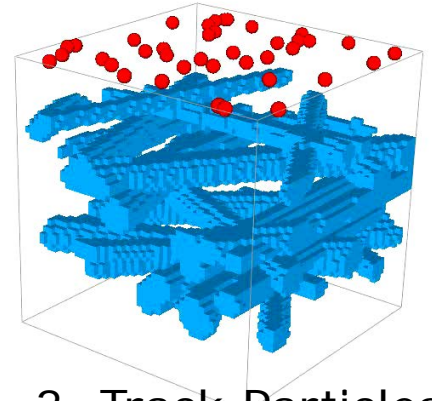
# Filter Life Time Simulation - Method



1. Filter Model

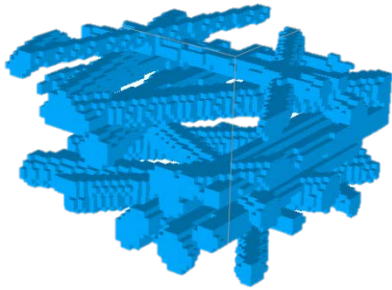


2. Flow Field

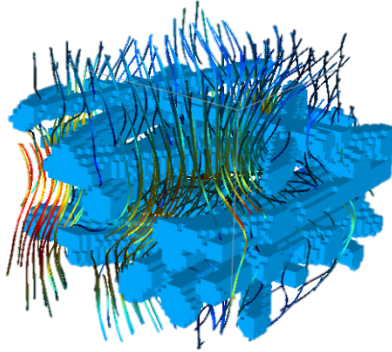


3. Track Particles

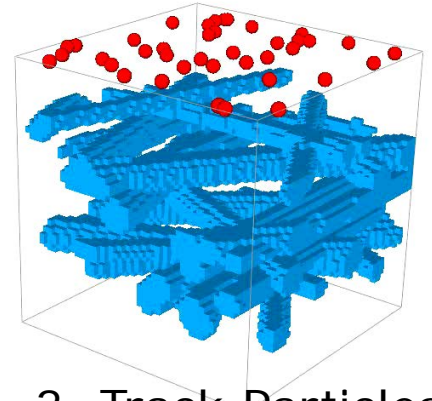
# Filter Life Time Simulation - Method



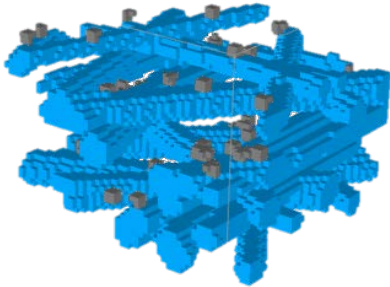
1. Filter Model



2. Flow Field



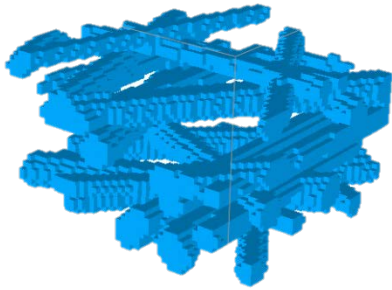
3. Track Particles



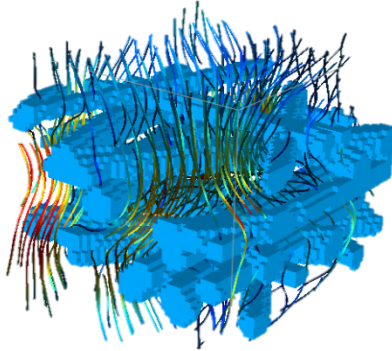
4. Deposit Particles



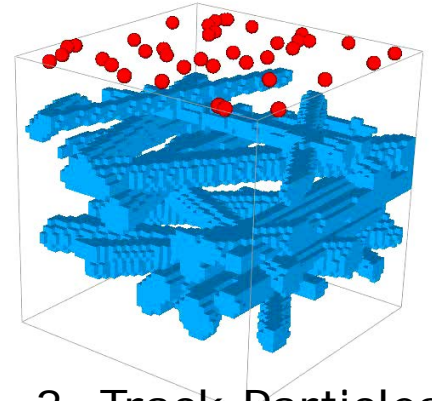
# Filter Life Time Simulation - Method



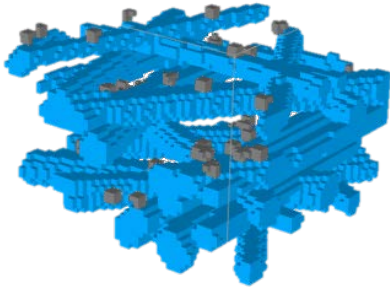
1. Filter Model



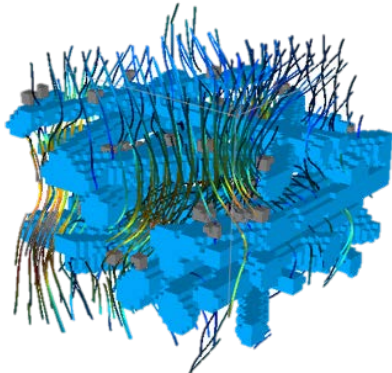
2. Flow Field



3. Track Particles

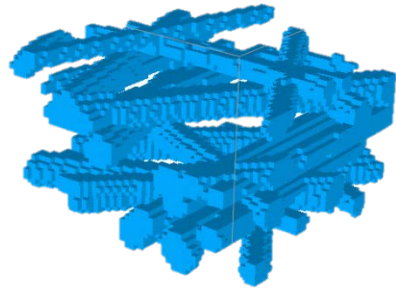


4. Deposit Particles

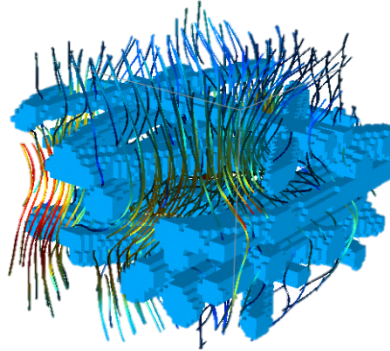


5. Recompute Flow

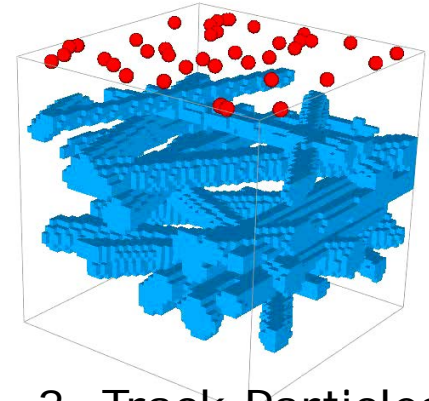
# Filter Life Time Simulation - Method



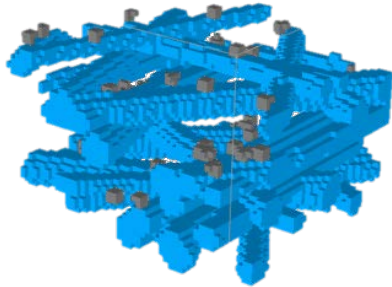
1. Filter Model



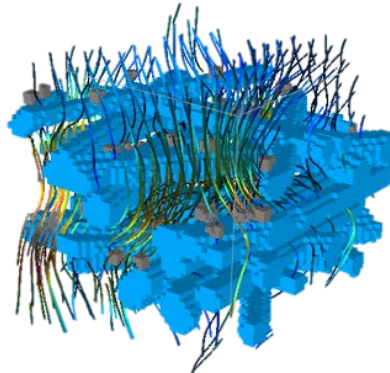
2. Flow Field



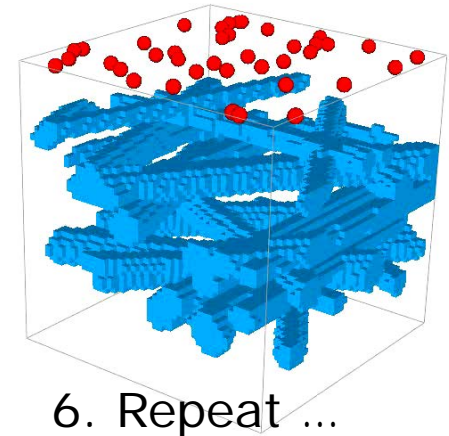
3. Track Particles



4. Deposit Particles



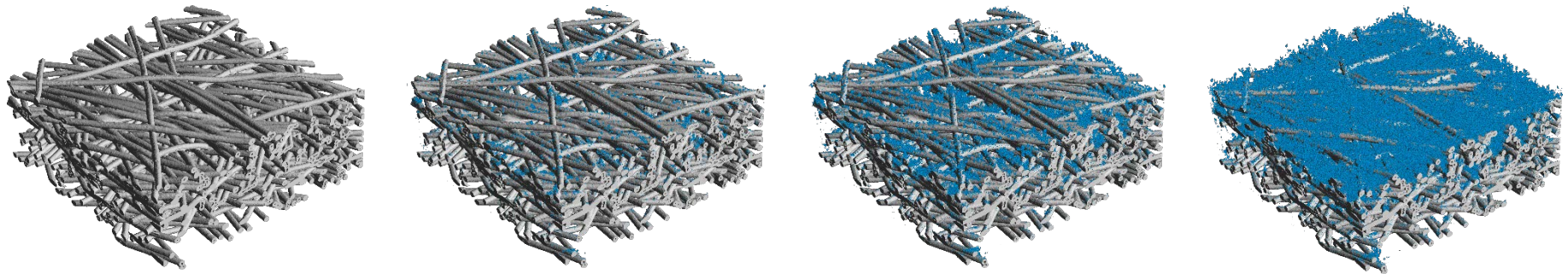
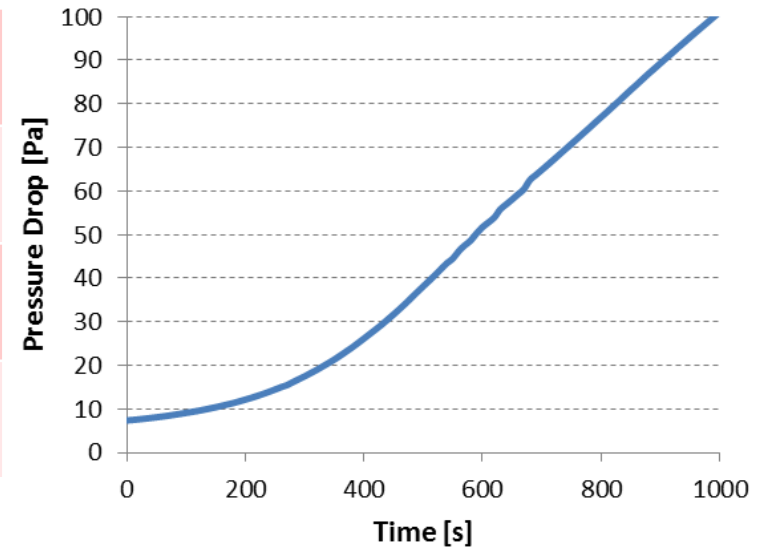
5. Recompute Flow



6. Repeat ...

# Cabin Air Filter - Life Time Simulation

Initial pressure drop	7 Pa
Pressure drop after 1000s	101 Pa
Total deposited dust after 1000s	93 g/m <sup>2</sup>
Total filter efficiency	93% (weight)



## **Step 2:**

**Create a model of the existing material**

# Creating a filter model

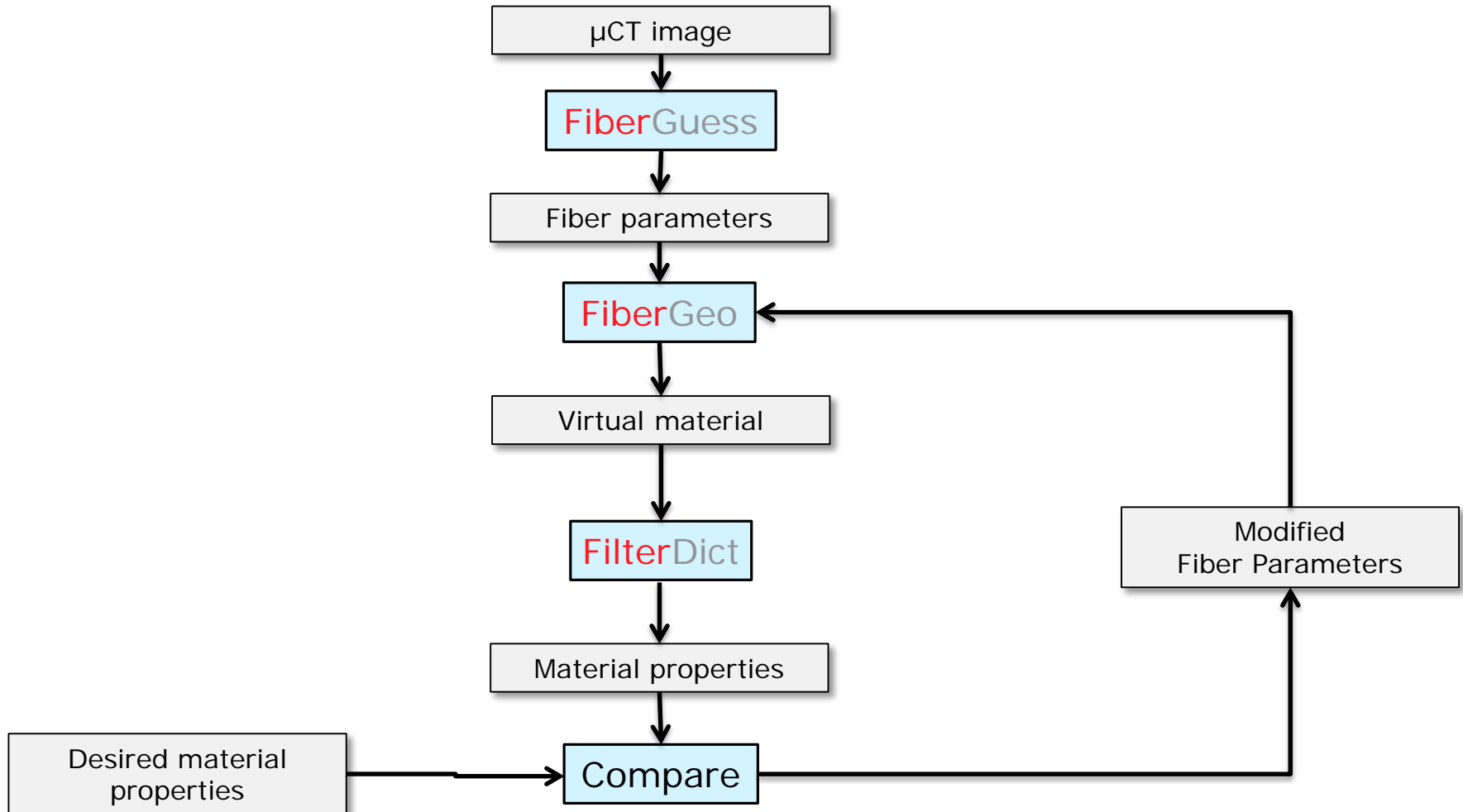
Why create a filter model?

- A CT scan is an image!
  - It can only be changed voxel-by-voxel.
  - It is not possible to remove a fiber
  - It is not possible to change diameters or shape

=> We need to “understand” the image!

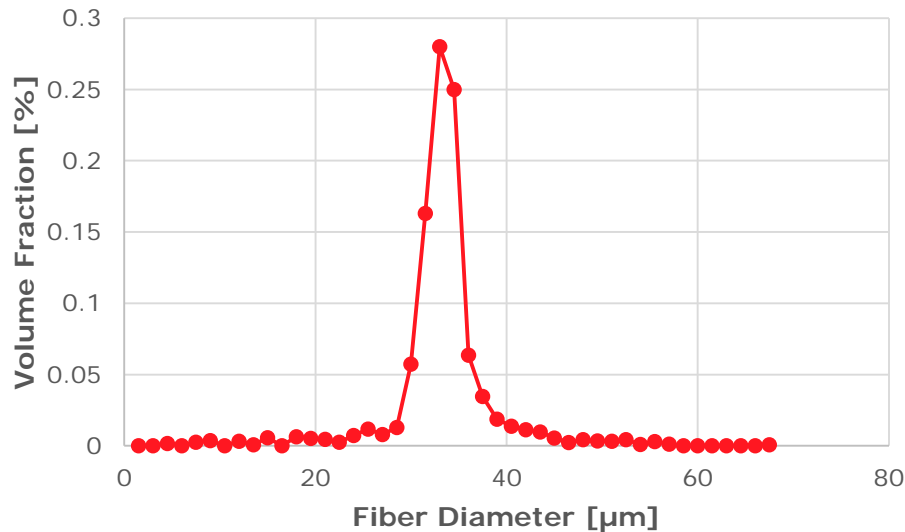


# GeoDict Workflow



# Geometric Analysis I:

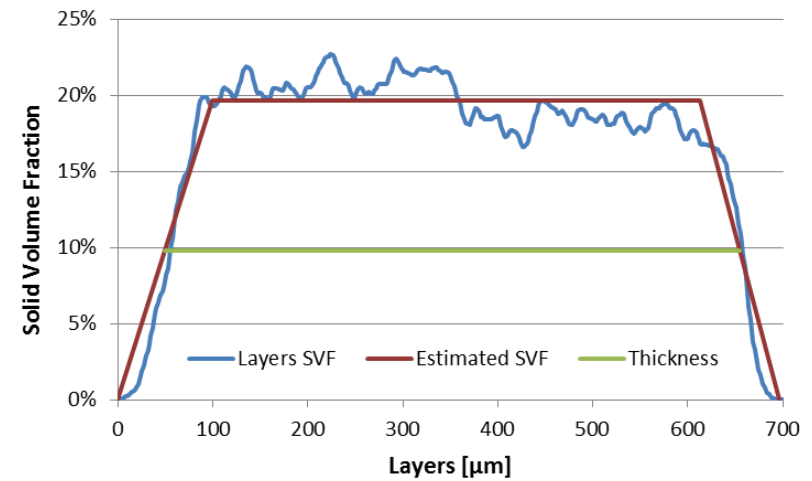
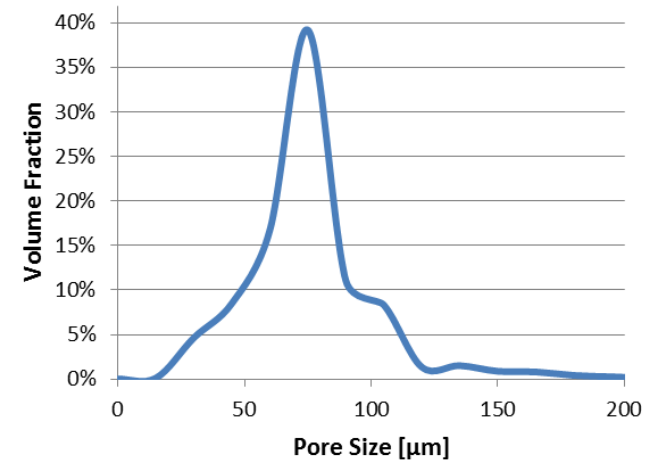
## Media Thickness, Porosity, Pore Sizes, Fiber Diameter



Average fiber diameter: 33.6 μm

Porosity: 80.4 %

Thickness: 605 μm





# Geometric Analysis II: Fiber Orientation

How is fiber orientation measured?



0.33	0	0
0	0.33	0
0	0	0.33



0.5	0	0
0	0.5	0
0	0	0

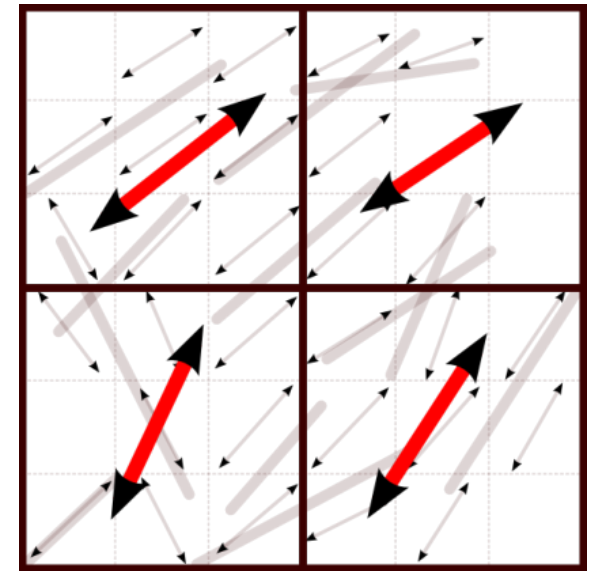
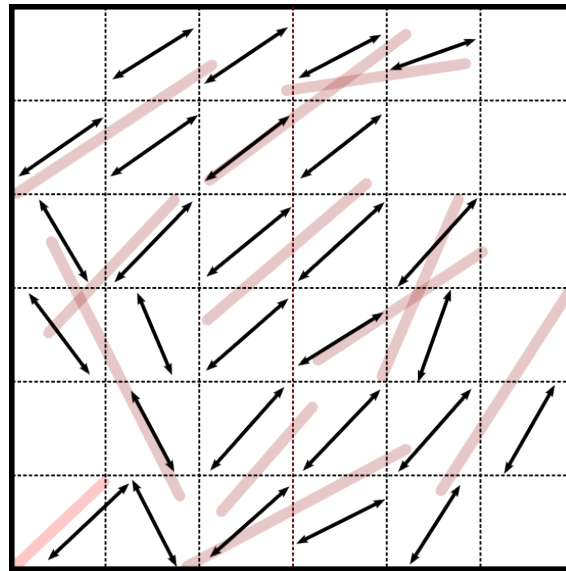
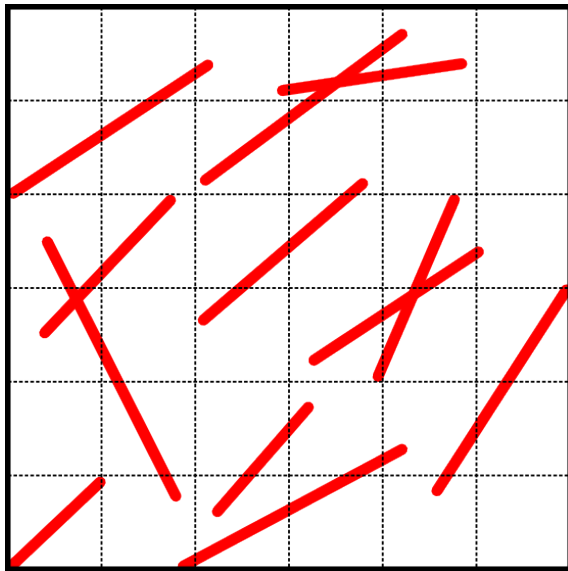


0.9	0	0
0	0.05	0
0	0	0.05

Orientation tensor describes probability of direction component.

# Orientation analysis – Method 1: Principal Component Analysis (PCA)

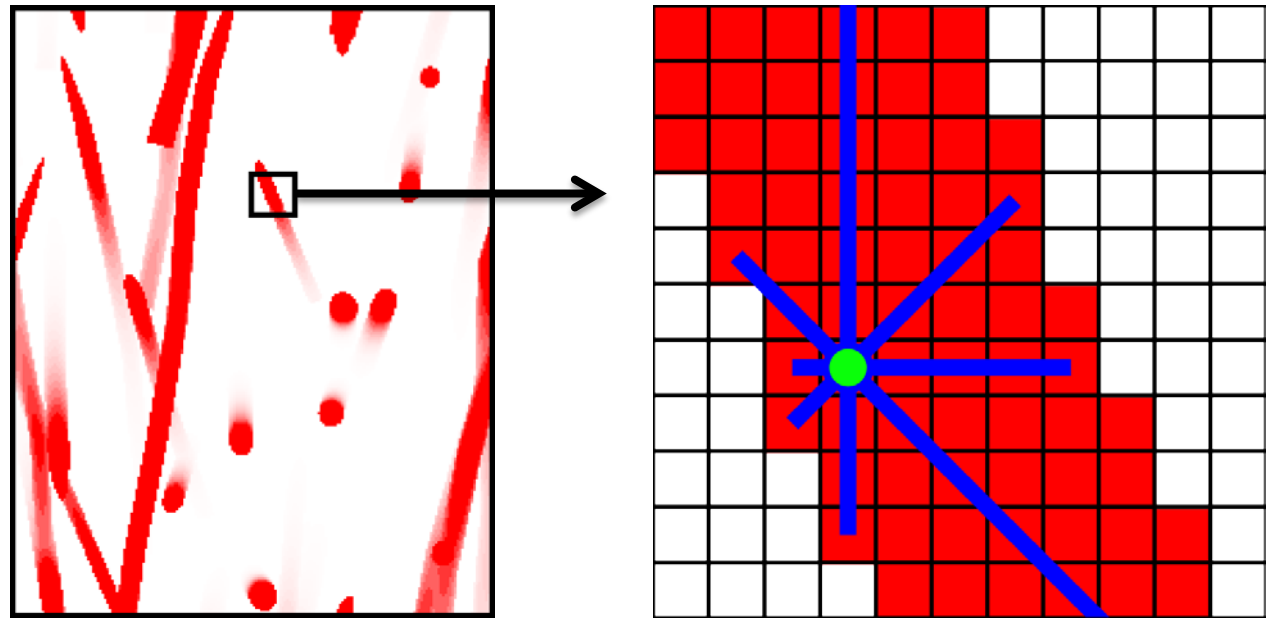
1. PCA subdivides domain into windows of given size
  - Automatic window size estimates about 2x fiber diameter
2. For each window, finds fiber fragments and analyzes direction tensor
3. For each block, averages direction tensors over windows in that block



## Orientation analysis – Method 2: Star Length Distribution (SLD)

- For each voxel, SLD analyzes chord lengths through it for fixed set of directions
- The relative length of the chords gives per-voxel orientation tensor
- The tensors are averaged over all voxels in the block (similar to PCA)

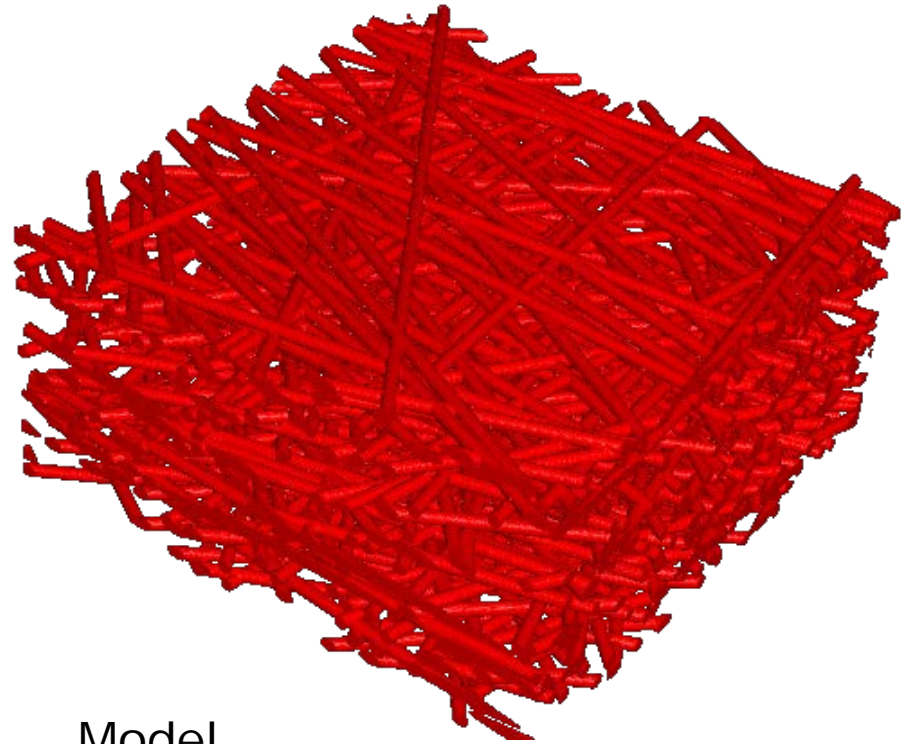
Smit, Th H., E. Schneider, and A. Odgaard. "Star length distribution: a volume-based concept for the characterization of structural anisotropy." *Journal of microscopy* 191 (1998): 249-257.



# Comparison of CT Scan and Model



CT Scan



Model

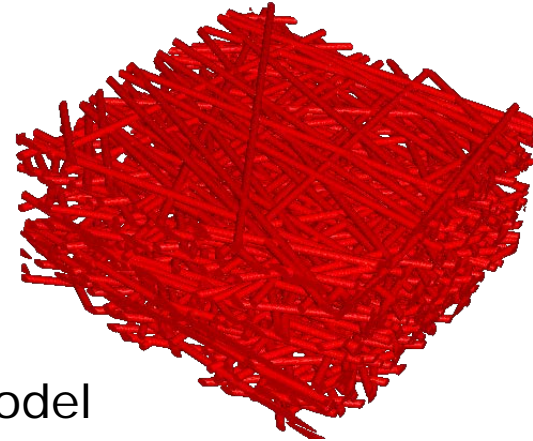
# Comparison of CT Scan and Model



CT Scan

Input parameters found by CT-Scan analysis:

- media thickness
- porosity
- fiber diameter
- in-plane anisotropy



Model

Input parameters taken from assumptions:

- straight fibers
- fibers oriented in-plane
- homogeneous distribution
- circular cross section





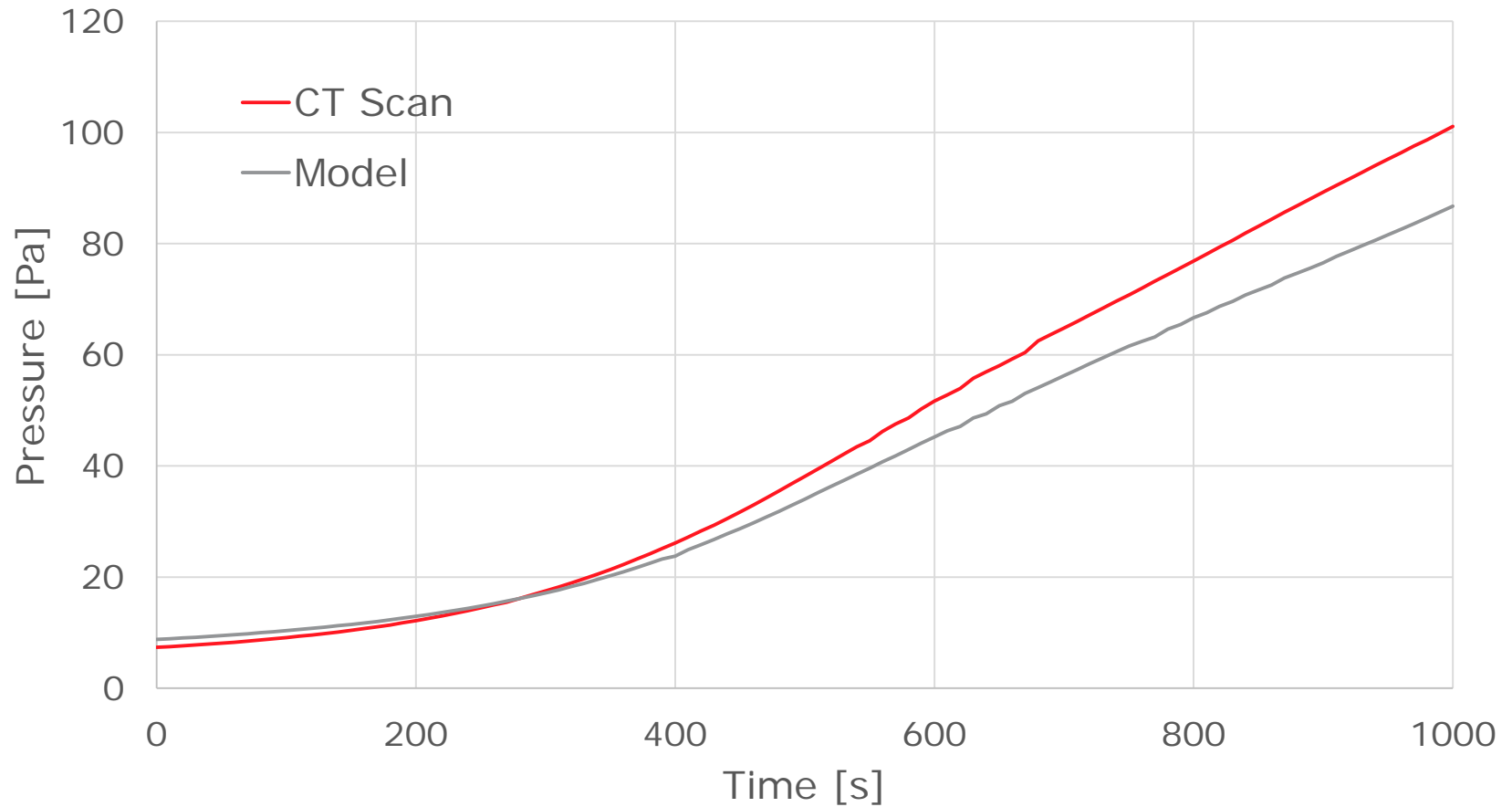
# Filter Life Time





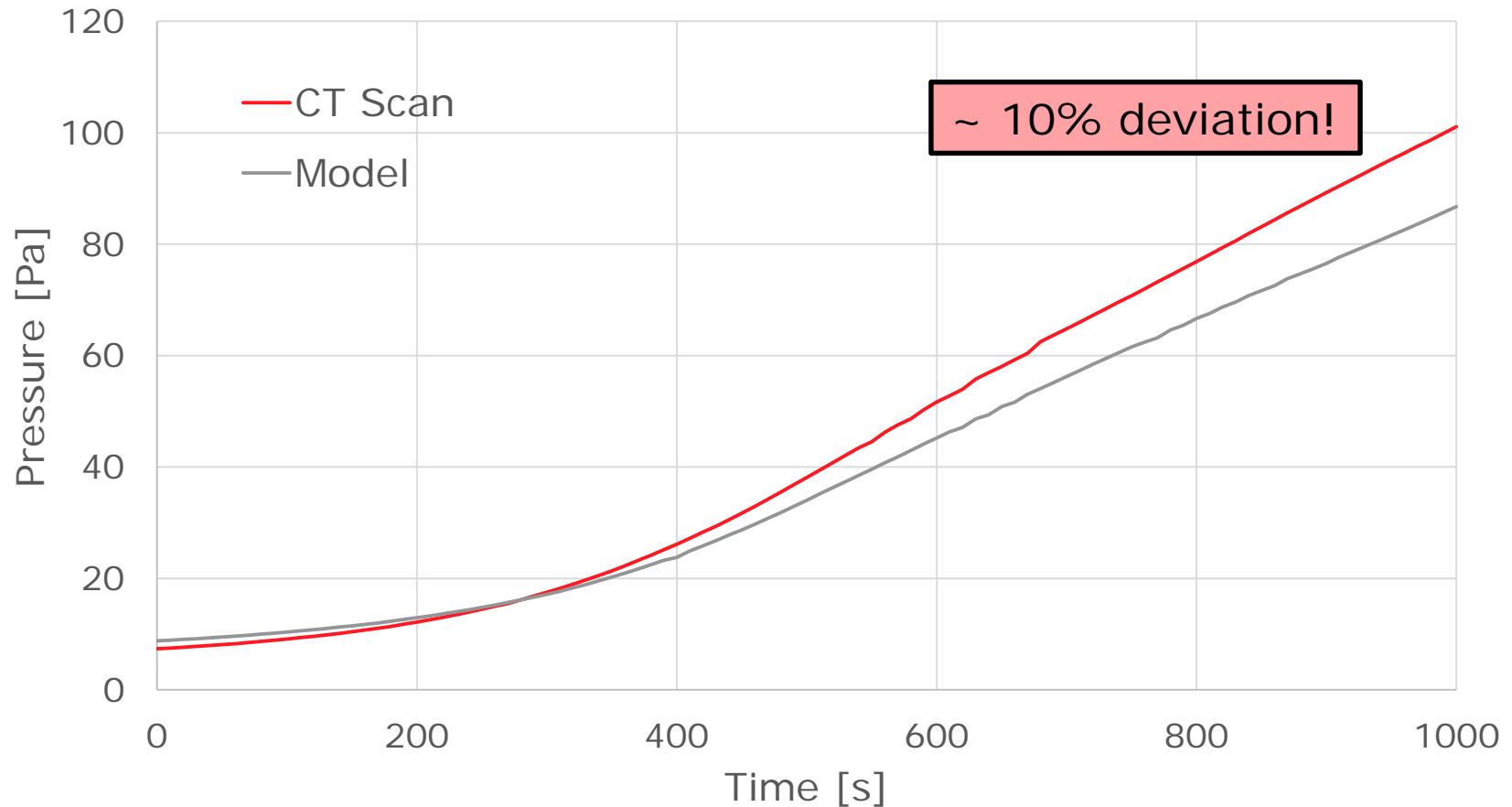
# Filter Life Time Simulation

## Comparison CT Scan vs Model



# Filter Life Time Simulation

## Comparison CT Scan vs Model



## **Step 3:**

**Modify the structure model**

# Possibilities in GeoDict to Vary the Structure Model

- Fiber diameter
- Fiber orientation
- Fiber cross sectional shape
- Curved fibers instead of straight fibers
- Density gradient in through-plane direction
- Porosity
- Media thickness

# Summary and Outlook

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Overall goal of this work:

- get from CT-Scan to Model structure automatically

Current state:

- works for straight fibers with circular cross section

Work in progress: curved fibers with circular cross section

- Determine curvature distribution from CT
- Realize given curvature distribution in a model

# GEO DICT

The Digital Material Laboratory

## Standard Edition

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Steffen Schwichow

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